Adam News Network EOS Programmer's Manual

Here it is! The EOS Programmer's Manual by Guy Cousineau. It's a very good document, and I hope that you find it useful.

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ELEMENTARY OPERATING SYSTEM PROGRAMMER'S GUIDE

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FOREWORD

The EOS (Elementary Operating System), is one of three operating systems available to the ADAM programmer. The other two, (CP/M (now replaced by the superior and user friendly T-DOS), and 057), are best suited for "work horse" or practical programs, and game graphics, respectively.

The EOS, the subject of this work, is a sort of bridge between the extremes of the "work horse" T-DOS, and the graphics game 0S7 operating systems. Thus the three operating systems complement one another.

Inasmuch as it is in the best interest of ADAM owners to have as many good programs for the ADAM as possible, (thus extending its usefulness, and thereby its practical lifetime), the ADAM News Network, (ANN), felt that it was desirable to publish a work that would help all interested parties write programs with the greatest facility that could be made available to them. ANN wants to encourage the ADAM owner to explore the field of Machine Language (ML) programming, and to encourage the development of ML programs. This work is designed to help ADAM owners use the EOS routines as correctly, and as effectively as possible.

Thus, through the generous work of Guy Cousineau, the author, this work is presented to help all who would, begin programming efforts to the benefit of us all.

The EOS, of course, must be addressed via ML instructions. There is, on the other hand, much to be said of the advantages of programming in the BASIC language. It is certainly easier to understand initially. But the direct use of ML programming instructions, though more time consuming perhaps, allows the writer to have program compactness, flexibility, and speed of execution, not possible by the use of any other programming language. Furthermore, some of the hardware specific functions on the ADAM can only be addressed by ML routines.

ANN also wishes to convey to all readers. and interested parties the understanding that the publication of this work is not the culmination of an EGO TRIP on the part of ANN or on the part of the author. If there are things found herein that are unclear, confuse, or clutter the mind, the reader is encouraged to write to, or otherwise get in touch with the ADAM community. Call the FIDO NET ADAM conference, any ADAM BBS, Compuserve, and direct whatever question you may have to the author or to any other ADAMite who might be in a position to answer such queries or implement your suggestions. No one will be offended. In fact, the contrary is the case:

ANN and its members encourage such dialogue.

Whether or not other works outlining the best uses of the 0S7 and the T-DOS operating system will. be published in the future will depend upon the response to this publication. ANN is dedicated to the promotion of anything that will help ADAM users. If a need is shown for such works, they will surely be forthcoming.

Having been requested to write this "INTRODUCTION", I would like to say that we are indeed fortunate to have Guy Cousineau as the author. I know Guy, and have worked with him on projects; I have always found him to be very personable and understanding. I personally have had to go back for repeated explanations of some items which he has written in the past, and found that he is not an AUTHORITY but a TEACHER. He has patience beyond reason, and tries very hard to help whenever he can. He is indeed an expert, but he is not an AUTHORITY who cannot bear to have his writings and. ideas questioned.

In his work, Guy does an excellent job of making the EOS routines understood. I have an original EOS manual, and have noticed that there are many invalid assumptions made there relative to the level of understanding of the reader.

Guy has clarified it greatly where things were nebulous.

We are fortunate indeed!

Mel Ostler

[ADDRESS REMOVED]

ACKNOWLEDGEMENTS

Before going any further, I feel obliged to. say thank you to all those who knowingly or not have made this work possible. This includes programmers from which I have picked up information or programming tricks, people who have encouraged me in my ML efforts, people who have published information on the ADAM operating system, and others who have generally been a support in my efforts on behalf of ADAM.

At the risk of forgetting some of the major contributors, I will list a few sources. If I leave any one out, it is definitely not intentional: consider yourself honourably mentioned in the above paragraph.

```
Tony Morehenfor getting me. involved in MLPeter and Ben Hinklefor their Hacker's GuidesBarry Wilsonfor starting up ANNMel Ostlerfor his books on ADAM and his introductionBruce Waltersfor his input on the sound routinesJames Waltersfor his help with sound and interruptsIan Cottrell(non-ADAMite) who has been a ML mentorRon Mitchellfor resurrecting the OTTAWA user's groupANN as a whole for reviving my interest in ADAMADAMITESfor encouragement by buying my software andasking all those "not so silly" questions
```

OVERVIEW

What is the EOS? It is the Elementary Operating System of the ADAM, and not the Extended Operating System, as some people call it. It consists of a series of routines which help the programmer interface with the hardware

attached to the ADAM. The EOS takes up the top 8K of memory and uses an additional 3K of buffers just below it. This 8K section has routines to address the keyboard, printer, screen, and storage devices. Each routine has a specific calling convention and may return information about the status of the operation or of the operating system itself.

The EOS is used by applications programs such as SmartBasic, AdamCalc, SmartFiler, etc. Other programs such as FileManager and other AJM software products (this is the only plug you will see in this manual) make use of the EOS to handle its elementary functions.

This manual talks a bit about the benefits of machine language programming, the EOS structure, and memory configuration. The greater part of the manual, however is devoted to the explanation of EOS routines. Not all routines will be covered. Some of the incomplete or non-implemented routines will be skipped so not to confuse the reader. It is intended as a reference tool for the machine language programmer, whether beginner or advanced. The first section deals with executive calls. As most application programs do not require these, it is recommended to skip over this section and come back to it later. Otherwise, you might try to absorb a lot of technical information which is not required. It has been placed first since it is logical in the sequence of operation.

Considering that Assemblers usually generate HEXADECIMAL codes, all addresses quoted in this manual will be in hexadecimal format only. This manual does not propose to explain Z-80 programming or the use of the Op-Codes. Someone with a knowledge of Z-80 programming will be able to use the manual to effectively access the operating system. In addition, some of the examples and complete programs/routines supplied in this manual may help the programmer pick up tricks about Z-80 programming or the EOS itself.

Please address any technical questions to:

Guy Cousineau

[ADDRESS REMOVED]

MACHINE LANGUAGE PROGRAMMING

Why use machine language programming? My three favourite reasons are SPEED, SIZE, and CONTROL.

By skipping superfluous steps and compressing operations into the most effective structure, you can achieve processing speed which has no match in any language, whether it be BASIC, Fortran, C, Pascal, etc. Think of the fastest BASIC routine you have seen to sort a series of strings. Then look at the speed of ADAMCALC's sort feature. The difference is amazing.

The programmer can effectively manipulate routines and common subroutines into a package that occupies less space than any other language. While some powerful BASIC programs may be quite short, consider that they have 27K of overhead: the BASIC itself! A Self-contained Machine language program can be written using only the EOS to handle console and file I/O. I have seen some self-contained machine language programs which take less than 1K and perform several functions.

Control is another key aspect of machine language programming. There is no need to assume that a particular SYSTEM routine (like BASIC's FOR, INT, etc.) will perform as they should. The programmer writes all his own support routines which perform the operation in the manner that suits the programmer's purpose. It is a bit more demanding but the outcome is usually a very efficient and compact program.

Bear in mind that when working with any language, the computer will ALWAYS do what you tell it to do; this is not always the same as what you intend it to do. It is much easier to throw the computer into a death spin when writing in machine language: you don't have SmartBasic checking your syntax and reporting other errors.

EOS STRUCTURE

The EOS uses a jump table to gain access to its functions. A jump table is a series of standard entry points which then pass control over to the routine that actually does the work The advantage of a jump table is that revisions to the operating system do not affect the addresses that the programmer uses to access the system's functions. The EOS routines can be subdivided into 9 categories, Each is composed of several routines to perform a specific series of tasks:

Executive Calls

These are the high level operations such as startup, device scanning, initialization, etc. Most of these routines are used on a cold boot to get the computer in running order. Additionally, self booting software will make use of some of these routines to set up the computer according to the programmer's requirements.

```
Console (Screen) Output
```

These routines take care of printing characters on the screen. They make use of the Video Ram routines outlined below.

Printer Interface

These routines take care of printing characters on the ADAM printer. Although parallel printer interfaces are available, the EOS had made no provision for this feature.

Keyboard Interface

These routines take care of fetching characters from the keyboard.

File Operations

These routines take care of disk/tape input output at the file level. Files can be created, opened, read, written to, closed, deleted, etc. in a fashion equivalent to the same commands in SmartBasic.

Device Operations

These are the routines which interact directly with the devices attached to the ADAM. They include the keyboard, printer, disk drives and tape drives. The Video Ram is not considered a device by the EOS.

Video Ram Management

These routines handle the movement of information (characters, sprites, shapes, colour, graphics, etc.) to and from video memory. It is these routines which actually put something on the screen.

Game Controllers

Since the joysticks are not devices, these routines handle the reading and decoding of information from the joysticks.

Sound Routines

The EOS has complex routines which are used by some software (like the arcade games) to generate elaborate sound effects.

MEMORY USAGE

```
FROM
      ΤO
             CONTENT
D390
      D3FF
             File Control Blocks
D400
      DFFF3 1K blocks used for directory and file I/O
E000 E1F5
             Video Ram routines
    E2C6
E617
ElF6
      E2C6
             Joystick routines
E2C7
             Sound routines
E618 F3D9 File routines
F3DA F445 Data used to INIT a medium
F446 F4B9 Device routines
F4BA F4FB Keyboard routines
F4FC F5D4
            Printer routines
F5DC F831 Screen routines
F832
      FA9D
             Executive routines
FA9E FBFD Device Control Block Routines
FBFF FC2F Data tables
FC30 FD5F JUMP TABLES
             Various data tables, storage, and stack
FD60 FEBF
FECO
           Processor Control Block
      FEC3
FEC4
             Device Control Blocks (one for each device)
      FFFE
```

The average program can use all memory below D390. This leaves the full EOS available to perform any function which many be required.

A program which requires additional memory may choose to use its own buffers for read/write operations. If it does not make use of the FILE routines, it may overwrite up to DFFF and gain an additional 3K of usable memory.

When even more memory is required, An application program may supply its own video drivers, and joystick routines (if required). It can then use memory up to F445 and gain another 5K. This leaves just the raw device drivers in the EOS. Provided no complicated video routines are required, this can be a viable alternative for very large programs.

EOS ROUTINES

This is the start of the technical section of the manual. It describes routines which can be accessed form the EOS jump table. For the sake of uniformity and ease of reading, each routine description will be on one page with the title of the routine at the top of the page. Descriptions will use the following format:

JUMP TA actual instruc	BLE ADDH address tion) an	RESS: The address to CALL. If you want to determine the of the routine, skip the first byte at this address (the JUMP and extract the REAL address from the next two bytes.
ENTRY:	A BC DE HL	Description of values which must be placed in registers to tell the function what to do. Only the relevant registers will be shown.
EXIT:	A BC DE HL	Some routines return information. The exit values will help you make the best use of the information provided. You will also note that some routines PRESERVE register values. This can be used to your advantage to save program space.

DESCRIPTION:

The description section will usually be in two parts: the first describes the purpose of the routine the second explain how the routine does its job. When a routine calls another major EOS routine, its name will usually be shown in UPPERCASE along with the page number in brackets.

EXAMPLES:

Where it can help illustrate the use of a routine, examples will be provided. These will be in machine language mnemonics with comments in the right margin.

INITIALIZE EOS

JUMP TABLE ADDRESS: FC30

ENTRY: none EXIT: B boot device number DESCRIPTION: ~ ~ ~

When you turn on the computer or pull the reset switch, the EOS is entered at this routine. This is the one that gets the computer in working order by setting the stack, initializing tables, setting up the devices, and checking for the presence of a boot tape or disk. While this function is used only at a cold start, a programmer may use it to reboot by prompting for an "insert media" and calling FC3O to clear memory and boot the media.

The routine starts by setting the EOS stack. It then nulls out all the data tables starting at FD6l. The EOS revision number is written to FD6O. It calls SET VDP PORTS(83) and SOUND OFF(104). It then nulls all the video RAM with a call to FILL VRAM(95) and switches in the normal memory configuration with a call to BANK SWITCH(20). The next step is to perform a HARD INIT(12) to set all the devices. Next is a call to INITIALIZE FILE MANAGER(41) which sets up the file management buffers. It then scans for the presence of media in disk 1, disk 2, tape 1, and tape 2 in that order. The first to contain media is presumed to be the boot media. Block 0 of that media is loaded at C800. The next step is very important: The device number of the boot media is placed in register B and a jump is made' to G800 where the media boot code can be executed. Boot code should store the boot device number so further media activity can be performed on the default media. If no boot media is found, a jump is made to the memory resident processor (electronic typewriter) via the JUMP TO SMARTWRITER(19) routine.

EXAMPLES:

To prompt the user to insert a disk or tape and perform a boot, you can use the following instructions:

LD HL, INSERTMSG ;prompt message. CALL PRINT ;your print to screen routine. GALL FC6G ;read keyboard (wait for character). JP FC30 ;do the EOS boot.

If you wish to boot a disk or tape without resetting the EOS tables or performing an initialization, you can replace the last instruction with a jump to F86A. Note that this is the direct address for EOS revision 5 and that it may not work on other revisions to the EOS. The BOOT device is still returned in B to the Boot block of the media. It is up to the programmer to pass the boot media to the main program. You could store it at (FD6F) which is the EOS-5 address of current device.

HARD INIT

JUMP TABLE ADDRESS: FC5D ENTRY: none EXIT: A destroyed BC \ DE preserved HL /

DESCRIPTION:

The function of this routine is to set the processor control block which in turn controls the allocation of device control blocks. It synchronizes the Z-80 processor with the 6801processor which controls the AdamNet.

This routine starts by initializing the Processor Control Block to FECO. Compare to the SOFT INITIALIZATION(18) routine which allows the user to set the PCB. It calls HARD RESET NET(13) and the DELAY(14) to initialize the system. The device control blocks are nulled out and a call to SYNCHRONIZE CLOCKS(15) is made. The final step is a call to SCAN FOR DEVICES(16) to allocate a DCB for each found device.

Although it would be considered a drastic measure, this routine could be called to effectively reset the ADAM and re scan all the devices.

EXAMPLES: none

HARD RESET NET

JUMP TABLE ADDRESS: FC60 ENTRY: none EXIT: A zero C reset port number others unchanged

DESCRIPTION:

This function does a hardware reset on the AdamNet. It gets the Net port number from location FC28 and sends a reset request (0F). It waits awhile and sends an idle command to the net. The routine returns the port number in register C but it is very unlikely that you will ever need this information.

This routine can be called to reset the net without clearing all the DCB's

EXAMPLES: none

DELAY AFTER HARD RESET

JUMP TA	BLE ADDRESS:	FC3C	
ENTRY:	none		
EXIT:	A others	0 preserved	

DESCRIPTION:

This routine pauses for 114 clock cycles. It is used after a network reset to make sure that the devices have time to idle down. With 3 million clock cycles per second, 114 is a blink of an eye for us but almost an eternity for the Z-80 processor. For some reason, the EOS designers did not include this delay as part of the HARD RESET NET(13) routine and the delay MUST be called for proper timing.

While the routine as-is has limited value, you can make use of it to create your own timed delays by patching directly into the routine. Remember the default values so you can restore them when you are through. Firstly, address F962 has a default value of 1. For the delay to have any substance, this should be reset to 0. Address F965 has a default value of 0. This is the one we can modify to create delays ranging up to 2.5 minutes.

VALUE 2 4 7	DELAY 1 2 4	VALUE 53 71 88	DELAY 30 40 50	1/2 minute
9	5	106	60	1 minute
18	10	212	120	2 minutes
36	20			

LD	A,0	
LD	(F962) ,A	
LD	A,53	
LD	(F965) ,A	;set 30 second delay.
CALL	FC3C	;do it.
LD	(F965) ,A	;note that A is zero (save an
instruction).		
INC	A	
LD	(F962) , A	

SYNCHRONIZE CLOCKS

```
JUMP TABLE ADDRESS: FCB1
ENTRY: none
EXIT: zero flag indicates success
A error code if NON-ZERO
others preserved
```

DESCRIPTION:

The purpose of this routine is to get ADAM's internals synchronized. Two synchronize requests are sent through the Processor Control Block. It is essential that these requests function properly. Otherwise, the ADAM NET may not function properly. The Synchronize Clock request must be sent each time the network is reset.

One of the byproducts of this function is to cancel out All active device control blocks. Thus a SCAN ACTIVE must be done after each synchronize clock function call.

EXAMPLES:

CALL FCB1 ;request the synchronize. JR Z,COOD ;the synchronization went ok.

;

;here you must decide how to handle the error

;you can call the function again or abort entirely

telling the user that ADAM has serious problems

;

;

GOOD:

CALL FC8A

;scan for active devices.

SCAN FOR DEVICES

JUMP TABLE ADDRESS: FC8A ENTRY: the Processor Control Block must be set EXIT: A zero others preserved

DESCRIPTION:

The purpose of this function is to find all the active devices on ADAM NET. It begins by zeroing out all Device Control Blocks. This will effectively remove devices which are no longer on line. On the other hand, the scan will pick up devices which have been powered up after the ADAM has turned on. Thus you should make sure that all devices are turned on before calling this function.

An area of 314 bytes is cleared above the 4-byte processor control block. It represents the 15 DCB's which are 21 bytes each. A count is kept in PCB+3 of the total number of devices found and a 21-byte DCB is set up for each device found. If you wish to check the number of devices found, you will have to FIND the PCB and examine its byte number 3.

EXAMPLES:

CALL	FC8A	;set up the DCB's.
CALL	FC5A	;get the PCB address into IY.
LD	A, (IY+3)	;number of devices.

;

;now you can tell your program or viewer

;how many devices you found

;

RELOCATE PCB

JUMP TABLE ADDRESS: FC7B ENTRY: HL Address to relocate PCB to EXIT: A 83H zero flag set BC preserved DE preserved HL new PCB address

DESCRIPTION

This function is used to relocate the Processor Control Block. Although I can see no particular reason for this function, COLECO must have thought that it might be a requirement with some of the expansion hardware or for special purpose applications.

The routine begins by getting the current PCB location since commands must still be sent through the current PCB location. The new address is written to the PCB data area and a SET command is sent to the NET. The routine then loops endlessly waiting for the net to acknowledge. If it does not, the system will hang up; there is no time out for this operation. The last step is updating the CURRENT PCB location in memory.

Once the PCB has been relocated, all devices are effectively put off line. You have to issue a SCAN FOR DEVICES (16) to restore all devices. I am not sure if it is necessary to perform a hard reset, but to be on the safe side, I would recommend using the SOFT INITIALIZATION(18) instead of this routine to relocate the PCB.

LO	н∟, 8000н	;address to relocate to.
CALL	FC7B	;move the PCB please.
CALL	FC8A	;scan for devices.

SOFT INITIALIZATION

JUMP TABLE ADDRESS: FC8D ENTRY: HL New PCB address EXIT: A destroyed others unchanged

DESCRIPTION:

The function of this routine is to set the processor control block which in turn controls the allocation of device control blocks. It synchronizes the Z-80 processor with the 6801 processor which controls the AdamNet.

This routine starts by initializing the Processor Control Block to the value supplied in HL. After that, its execution is virtually identical to HARD INIT(12). It does a hard reset, a delay, a synchronize, and a scan for devices.

Since you need to do all these housekeeping functions when you want to relocate the PCB, it is best to call this vector instead of RELOCATE PCB.

EXIT TO SMARTWRITER

JUMP TABLE ADDRESS:FCE7

ENTRY:	none
EXIT:	none

DESCRIPTION:

This is the routine used by the COLD BOOT sequence (power up) when no bootable media is found. It bank switches in the SMARTWRITER ROM and jumps to it. If you wish to abort a program you can call this routine to effectively halt all operations.

Since this routine does a BANK switch, it is essential that the STACK be located in upper memory when it is invoked. Although it is not a standard location, I suggest using 65535 since it is used only temporarily and the SmartWriter will set its own stack when it takes over.

CALL	ABORTYN	;ask user to abort.
RET	ΝZ	; changed his mind.
LD	SP,FFFF	;set stack to upper half.
JP	FCE7	;let's get out.

SWITCH MEMORY BANKS

JUMP '	TABLE	ADDRESS:	FD14	
ENTRY	:	A	desired memory	configuration
EXIT:	A B C DE HL	current current memory preserv preserv	configuration configuration port number ed ed	

DESCRIPTION:

This routine can switch either the upper or the lower 32K of memory to any of 4 configurations. It simply sends the requested configuration to the memory bank switch port. Although it is a simple routine, it is easy to get into trouble with it. When the memory configuration is changed, program control may wind up in the switched bank with unpredictable results. Since the EOS is in the top half of memory, the TOP HALF should never be switched using this routine. If you do, the EOS will effectively disappear, and your program will crash. It is also essential that the Routine which calls this function be also located in the upper half of memory (above 8000H) or program control will also be lost.

Consult the appendix for ADAM's memory bank configuration.

EXAMPLES:

This is the breakdown of the routine used to switch banks. If you wish to switch in the upper half of memory, you will require a routine similar to this in the lower 32K to make the switch.

LD	A, (FC27) (SAVE) >	;get the port number.
<u>и</u>	(SAVE) ,a	, save the address in rower memory
somewhere.		
LD	С,А	;put port in C.
LD	A,config	;put in the configuration you want.
OUT	(C)	;switch it over.

;

:

;do what you wish to do in here

```
LD A, (SAVE) ;get the port back.

LD C,A

LD A,normal ;bring the EOS back into top half.

OUT (C) ;send request to port.
```

CONSOLE OUTPUT

INITIALIZE CONSOLE

JUMP TABLE ADDRESS: FC36 ENTRY: B number of columns (0 to 31) C number of lines (0 to 23) D home column E home row HL pointer to pattern name table

EXIT: all registers lost

DESCRIPTION:

This routine is used to set up a WINDOW for screen display. Registers B and C contain the, number of rows and columns while registers D and E contain the upper left corner of the window. The other parameter required is base address of the Pattern Name Table. If you have previously set up VDP, you should have NOTED what that address was. If you; are using a routine in conjunction with SmartBasic, the default pattern name table address is 1800H.

The routine stores lines and columns, sets up minimum and maximum values for ROW and COLUMN based on the supplied parameters. You can set up many windows and jump around between them by repeating calls to this routine. When this routine exits, the default cursor (an underline) is placed in the top left corner of the window. You can then send a move cursor command (see console display page 18) to place it at the appropriate location in the window.

EXAMPLES:

This routine sets up a 12 line window in the centre of the screen:

LD	в,20	;20 columns.
LD	C,12	;12 rows.
LD	D,6	;home column.
LD	Е,6	;home row.
LD	нь, 1800н	;or whatever your pattern address is.
CALL	FC36	;set up the screen.

CONSOLE OUTPUT.

CONSOLE DISPLAY REGULAR

JUMP TABLE ADDRESS: FC33

ENTRY: A character to send

EXIT: all registers preserved including A

DESCRIPTION:

This routine prints whatever character is in the accumulator to the screen. It presumes that the VDP has been set up and that a window has been defined. It will print ALL characters including the graphic representation of the control codes (0-31). If you wish to send a control CODE, use the routine on the next page.

The routine first sends the character to video RAM. Then it advances the cursor position, going to the next line if required. If the cursor is on the last line, the screen is scrolled.

EXAMPLES:

This subroutine is used to print an incoming message in register HL. It presumes that the string to print is followed by a null (ASCII 00).

PRTSTR:

LD OR RET CALL INC JR	A, (HL) A Z FC33 HL PRTSTR	;the string was over. ;print the thing. ;remember HL was preserved. ;loop until end of string.
--------------------------------------	---	---

CONSOLE OUTPUT

CONSOLE DISPLAY SPECIAL

JUMP TABLE AD	DRESS: FC39
ENTRY: A D E	character to print or PLACE CURSOR request column to go to if PLACE CURSOR row ,to go t9 if PLACE CURSOR
EXIT:	all registers preserved including A

DESCRIPTION:

This routine, like console display on previous page will print a character on the defined window. It begins however by checking for 12 special control codes. If it finds one of these, it executes the following control functions:

CONTROL CRARACTER	KEYBOARD EQUIVALENT	FUNCTION PERFORMED
08	BACKSPACE	move cursor left one
0A	^J	move cursor down one line (line feed)
0C	^L	clear screen and home cursor
0D	RETURN	return cursor to start of line
		(must send line feed if new line wanted)
16	^V	delete to end of line
18	^X	delete to end of screen
1C	^\	place cursor at position DE
80	HOME	home the cursor (no clear)
A0	up arrow	move up
Al	right arrow	move right
A2	down arrow	move down
A3	left arrow	move left

Note that there is no CURSOR ON or CURSOR OFF. In EOS-5, you can replace 3 bytes starting at F658 with. ZEROS to turn the cursor off. Be sure to remember the values to turn it back on again.

EXAMPLES:

When the string STRING is printed, it will send the cursor home, skip 2 lines, print HELLO, and clear the rest of the screen. Note that the first two lines would not be erased by this operation:

LD HL,STRING

REPEAT:

LD A, (HL)

		OR	A
		JR	Z,CONT
		CALL	FC39
		INC	HL
		JR	REPEAT
STRING:	DB	80H,A2H,	A2H, 'HELLO' ,18H,0
STRING:	DR	80H,A2H,	A2H, 'HELLO' ,18H,0

CONT:

;Program continues here

PRINTER INTERFACE

PRINT CHARACTER

	JUMP TA	BLE ADDRESS: FC66
ENTRY:	А	character to print
EXIT:	A others	zero flag set - successful error code if NZ preserved

DESCRIPTION:

This routine sends one character to the printer. Compare to print buffer on next page.

If the printer is not found, error code number 1 is returned in the accumulator. This means the NET does not know the printer is there. You should re scan for active devices and if the printer is still not found, you should abort with a warning to the user.

If the printer is busy, the routine returns error code number 2 in the accumulator. You can wait a bit and retry.

If the printer is off-line (i.e. not working), error code 3 is returned. If this happens, do NOT retry; it will serve no purpose.

If the printer is ready, the character is placed in the print buffer and the printer is asked to print it via the PRINT BUFFER routine on the next page.

EXAMPLES:

RETRY:

LD	A, character	;what you want to print.
CALL	FC66	;ask printer to do it.
JR	Z,GOOD	
AND	127	;strip acknowledge bit if any.
DEC	А,	;was A one?
JP	Z,NODCB	;try and find the printer
DEC	А	;was A two?
JR	Z, RETRY	;let's loop until it works.
DEC	А	;was A 3?
JP	Z,PTRDIED	;printer died? Now what do we do?

GOOD:

;

;continue program

PRINTER INTERFACE

PRINT BUFFER

JUMP TABLE ADDRESS: FC63

ENTRY: HL pointer to string (terminated with ASCII 03)

EXIT: Zero Flag set - successful A error code if non-zero others preserved

DESCRIPTION:

This routine will print a string pointed to by register HL. The bytes are sent to the printer in groups of 16. If the string (or remainder) is less than 16 then the partial string is sent and then the routine exits. You can use this routine to print strings of any length: an entire document if you wish. The nice thing about it is that you only need to place a "03" at the end of the string.

The routine stays in control until the entire string is printed. Since the printer is a very slow device, you may choose the alternate method using START WRITE and END WRITE explained on the following pages. The error codes are the same as for PRINT CHARACTER:

1	No printer
2	Printer busy
3	Printer off line (idle)

EXAMPLES:

This is an example of a subroutine used to print a string. The subroutine expects HL to point to the data and takes care of errors:

LD	HL,STRI	NG	;print this.
	CALL	PRINTIT	;ask subroutine to do it

.

;

PRINTIT:

CALL	FC63	;print the whole thing.
RET	Z	;OK
AND	127	;strip acknowledge bit.
DEC	А	
JR	Z,NOPRINT	;No DCB found.
DEC	A	
JR	Z, PRINTIT	;retry.if busy.

; if we get here then the printer is off line.

NOPRINT:

; if we get here then try FINDING the printer again.

PRINTER INTERFACE

PRINTER STATUS

JUMP TABLE ADDRESS: FC84	
ENTRY: none	
EXIT: Zero flag set - READY A error code if non zero IY address of DCB (only if no error) others preserved	

DESCRIPTION:

Although it might be considered a bit of a waste, this is a handy routine to use. You don't need to remember the DEVICE number of the printer(2) and call REQUEST STATUS.

If you wish to check the availability of the printer prior to sending a character or string, use this routine. When used in conjunction with the routines on the next pages, it allows you to do other things while you are waiting for the printer to be READY.

The most common errors are

1	no DCB
2	busy (it is printing something)
3	off line (idle)

EXAMPLES:

This routine waits for the printer to be ready and then sends the character in A to be printed.

LD C,A ;save the character.	
-----------------------------	--

RETRY:

C J	CALL R	FC84 Z,READY	;check status.
A	AND	127	;strip acknowledge bit if any.
C	CP	2	
J	R	Z, RETRY	

;

;process other errors here.

;

READY:

PRINTER INTERFACE

START PRINT CHARACTER

JUMP TA	BLE ADDI	RESS: FC9F
ENTRY:	А	character to print
EXIT:	A others	Zero flag set - successful error code if non-zero preserved

DESCRIPTION:

This routine is used to set up background printing. If the printer is READY, it asks it to print a character and returns the control to the user. Since the printer is very slow, you can perform a few other tasks and use END PRINT CHARACTER to check if the printer is done.

The error codes are the same as the other print routines.

EXAMPLES:

This subroutine expects a character to print in A. It sends it to the printer first (since it is slow); then to the screen. Finally it waits until the printer is done prior to returning.

LD	C,A	;save the character.
CALL	FC9F	;start print.
JR	NZ, PERR	
LD	A,C	;get character back.
CALL	FC66	;print to screen.
JR	NZ,SERR	

RETRY:

CALL	FC42	;is printer done?
JR	NZ,PERR ;r	nust check error FIRST.
JR	NC,RETRY	; if no error and not completed then wait.
	RET	;yes we are finished.

PERR: ;process printer error here.

SERR: ;process screen error here.

PRINTER INTERFACE

END PRINT CHARACTER

JUMP TABLE ADDRESS: FC42

ENTRY: none

EXIT: CARRY SET completed NO CARRY and ZERO not completed NON ZERO error A error code if no carry and non-zero others preserved

DESCRIPTION:

This is the companion routine to start print character. It finds the DCB and returns an error if not found. It will also return an error if the printer is off line or is busy. If the printer is done, the carry flag is set prior to returning to caller.

This routine does not retain control while a character is being printed. It allows the programmer to do some coprocessing.

EXAMPLES:

The routine shown in start print buffer is not the most effective way of maximizing throughput since the print routine does only one task and spends the rest of the time waiting. Once it is done, the programmer still uses valuable processing time to FETCH another character to send to the routine. Another approach is to send the FIRST character to print using START PRINT and not check for completion. All subsequent characters can be sent to this routine which waits for the first to be done prior to sending another.

	LD CALL	A,CHAR FC9F		;this is the first character printed.
;				
;				
	LD	A,CHAR CALL	PRINTC	;all subsequent chars to this routine.
;				
;				
PRINTC:				

	LD	C,A	;save new character to send.
WAIT:			
	CALL JR JR LD CALL RET	FC42 NZ,PERR ;oops. NC ,WAIT A,C FC9F Z	;end print the last one? ;start to print this one. ;good start.

;here we have a printer problem.

RET PERR:

PRINTER INTERFACE

START PRINT BUFFER

JUMP TABLE ADDRESS: FC9C

ENTRY:	HL	points to a string terminated with ASCII 03
EXIT:	A others	Zero Flag set - success error code if non-zero preserved

DESCRIPTION:

This routine was intended to print up to 16 characters on the printer in background. It requires the use of the companion END PRINT BUFFER routine on the next page. The routine starts by finding the printer and returns an error if the printer is not found or busy. It then looks through the input string for a 03 in the first 16 characters. If none is found, it STARTS to print the first 16 characters. The routine may have been intended to handle longer strings since it keeps track of where it is (when longer than 16).but does not seem to have been fully implemented.

Since the ADAM printer is slow, you will have about a second and a half (almost an eternity for the Z-80) to perform some other work while the printer is busy doing this task. You can periodically check if the printer is done and then send more characters When you send your last 16 (or less), you can just carry on doing something else, provided you check if the printer is done prior to starting another print sequence.

EXAMPLES:

See example on next page which sends a LONG string to the printer.

PRINTER INTERFACE

END PRINT BUFFER

JUMP TABLE ADDRESS: FC3F

CARRY SET

NO CARRY

NON ZERO

Α

others

ENTRY: none

EXIT:

completed and ZERO not completed error error code if no carry and non-zero preserved

DESCRIPTION:

This is the companion routine to START PRINT BUFFER(33). It allows you to perform other tasks and check if the printer is done the 16 (or less) characters you sent. Once completed (or error), you can send another with START PRINT BUFFER(33).

EXAMPLES:

The following routine sends a LONG string (which has a 03 at the end) to the printer. It makes use of the wait time to call another routine which could perform any small task.

PUSH ID ID	HL A,3 BC,65535		;save start	of string.
	CPIR			;find the 03.
LD	HL,0			
OR	А			
	SBC	HL,BC		;this is the number of characters
SRL	Н			
RR	L			
SRL	Н			
RR	L			
SRL	Н			

RR	L		
SRL	Н		
	RR	L	;this is the number of 16-byte packets to send.
LD	B,H		
	LD	C,L	
	INC	BC	;correct count
	POP	HL	;get back original pointer;

MORE:

	CALL FC9C	;start to print.	
JR	NZ,ERROR		

WAIT:

CALL CALL JR JR	ABCD FC3F NZ, ERROR NC,WAIT	;routine better save BC and HL. ;is printer done?
LD	DE,16	
ADD	HL,DE	;advance pointer
DEC	BC	
LD	A,B	
OR	С	;is BC zero?
JR	NZ,MORE	

KEYBOARD INTERFACE

KEYBOARD STATUS

JUMP TABLE ADDRESS:		FC81
ENTRY:		none
EXIT:	Zero flag s A IY others	eet - no errors error code if non-zero address of DCB (only if no error) preserved

DESCRIPTION:

This routine is used to find out if the keyboard is active. It will return a 1 in the accumulator if there is no DCB. This means that the keyboard was not found. It may indicate hardware failure or just that the keyboard was not plugged in when the system was turned on. Error code 3 means that the device is idle.

While it may be useful to check the keyboard status in this manner, you still need another EOS call to actually fetch a character from the keyboard. This routine could be used in a power up sequence to ensure the keyboard is there.
KEYBOARD INTERFACE

READ KEYBOARD

JUMP TABLE ADDRESS: FC6C

ENTRY: none

EXIT: Zero flag set - no error A character if non zero else it contains the error code others preserved

DESCRIPTION:

This routine starts by calling START READ KEYBOARD(28). If this fails, an error code is returned. The routine then keeps calling END READ KEYBOARD(29) until a character or an error is received. The routine remains in control until a key is pressed; this is like SmartBasic's GET command.

For simple keyboard input, this routine is adequate. It should not be intermixed with the START and END read commands as you may wind up missing a character.

EXAMPLES:

This routine requests characters from the keyboard and places them in a buffer at (HL) until <RETURN> is pressed.

LD	HL,BUFFER	;point to a memory area for data.
CALL	GETENTRY	;fill it up please

;

;more program here.....

;

GETENTRY:

CALL JR LD CP RET INC JR	FC6C NZ, ERROR (HL) ,A 13 Z HL GETENTRY	;read keyboard. ;something went wrong. ;save character even if <cr> ;yes we have a full entry. ;get another character.</cr>
--	---	---

KEYBOARD INTERFACE

START READ KEYBOARD

JUMP TABLE ADDRESS: FCA8

ENTRY: none EXIT: Zero flag set - successful A error code if non-zero others preserved

DESCRIPTION:

This routine asks the keyboard to fetch a character. The Keyboard will not acknowledge until it a key has been pressed. After that, the only thing the programmer needs to do is call END READ KEYBOARD(39) to see if there is a character waiting.

If there is no DCB or the keyboard is off line, an error code will be returned.

EXAMPLES:

see page 39

KEYBOARD INTERFACE

END READ KEYBOARD

JUMP TABLE ADDRESS: FC4B

ENTRY:	none		
EXIT:		No Carry Carry set Zero flag set A	no character waiting. we have an answer (could be an error). No error. keyboard character if carry set. error code if zero flag set.

DESCRIPTION:

This routine asks the keyboard what is happening. It returns a complex set of readings using the Carry and Zero flags. It is important to check these in the correct order to trap all the conditions. First, check the carry flag to see if the operation is complete. The next step is to check the zero flag for errors.

A combination of START and END read is the most effective way of reading the keyboard since it allows you to check the keyboard for an interrupt command while some other process is ongoing (similar to catching CONTROL-S when listing in SmartBasic).

EXAMPLES: Routine to check for abort within a process.

IGNORE:

	CALL	FCA8	;start read (only if not previously done).
JR	NZ,ERRO	OR	
MORE:			
	CALL	PRINTCHR	;send once character to the screen/printer.
CALL	FC4B		; is there anything?
	JR	NC,MORE	;so let's print some more.
JR	NZ,ERRO	OR ;we have	a keyboard error.
CP	19		;is it CONTROL-S?
JR	Z,WAIT	;wait unti	l other key pressed.
CP	3		;is it CONTROL-C?
	JR	NZ,IGNORE	; if not ignore key but reset read.

;abort code goes here.

Routine to wait for a character and return it in B.

STARTGET:

CALL	FCA8	;enter here is need to start the keyboard.		
	JR	NZ,ERROR	;start read.	

WAITCHAR:		;enter here if start already done.
CALL	FC4B	;end read.
JR	NC ,WAITCHAR	;wait until acknowledge.
JR	NZ, ERROR	;bad keyboard again.
LD	B,A	;save character.
CALL	FCA8	;restart read for next time.
JR	NZ, ERROR	
RET		

INITIALIZE FILE MANAGER

JUMP TA	BLE ADDI	RESS:	FCBA
	ENTRY:	DE	pointer to 3K of memory for FCB transfer buffers
	HL	pointer to	105 bytes for three File Control Blocks
	EXIT:	all register	rs preserved

DESCRIPTION:

This routine establishes three file control blocks and 3 1K buffers for the data sent/received through the FCB's. It also sets up and sets to AVAILABLE three 35 byte file control blocks.

The EOS INIT sequence sets up three default FCB's and buffers. programmer, however, may wish to move these elsewhere.

EXAMPLES:

This routine shows the default setup for the FCB's:

LD	HL,D390	;reserve 112 bytes for FCB's (round number?)
LD	DE,D400	;3K ending at EOOO.
CALL	FCBA	;set up file manager.

CHECK DIRECTORY FOR FILE

JUMP TA	BLE ADDR	ESS: FCFC
	ENTRY: HL	A device pointer to file name
EXIT:	A BC DE HL	Zero flag set means file found error code if non zero Start block of file if found preserved

DESCRIPTION:

This routine ALWAYS uses the first file control block which is reserved for directory work. It sets the FCB to read block 1 of the medium which is presumed to be the directory. It extracts the directory size from byte 12 of block 1 of the media. The next step is to check if this is a directory by looking for the 55 AA 00 FF at bytes 13, 14, 15, and 16. It then updates the file counters and begins searching for the file name. First, it looks for a BLOCKS LEFT entry; if found, the routine aborts with error code 5 in A. Deleted entries are also skipped.

The next part is to compare the file name with the user supplied name in (HL). The search routine has the capability of skipping the FILE TYPE byte based on a flag at FDD8. If non-zero, then the file type is expected to match. In order to set this flag properly, you should use the FIND FILE 1 or FIND FILE 2 routines.

The routine continues scanning entries, reading additional blocks if necessary in order to find the file. If the file is found it's start block is placed in registers BCDE and the file name is preserved in HL.

EXAMPLES:

LD	A,8	;read tape 1.
LD	HL, FILE	;look for this file.
CALL	FCBA	;find the file.
JR	Z,FOUND	
СР	5	
JR	Z,NOTFOUND	;reached BLOCKS LEFT.

;

;interpret and process other errors like bad block here.

;

FILE: DB 'thisfileA',03 ;note the file type and the 03.

FIND FILE 1

```
JUMP TABLE ADDRESS:
                               FCCC
       ENTRY:
                      А
                              device
               pointer to file name
       DE
               pointer to user buffer
       ΗL
EXIT:
               Zero flag set means file found
       Α.
               error code if NZ
       BC DE file start block if found
               directory entry if found
       (HL)
       ΗL
               preserved
```

DESCRIPTION:

This routine looks for a match of a file name and file type. To search only for a name, use FIND FILE 2 on the next page It sets the search flag and calls CHECK DIRECTORY FOR FILE (42). If the file is found, it copies 23 bytes from the directory entry (excluding the date bytes) to the user buffer pointed: to by HL. Registers BCDE also contain the start block of the file.

While this routine may be more informative than CHECK DIRECTORY, the programmer must ensure that incoming registers are properly set. Note also that this routine uses DE to point to the name while the other uses HL.

EXAMPLES:

This routine finds a file and determines the size of the file (in blocks).

	LD LD CALL JR PUSH POP LD LD	A,4 DE,FILE HL, BUFFER FCCC NZ,ERROR HL IX L, (IX+19) H, (IX+20)	;point ;store	<pre>;use disk 1. to the file name. the entry here. ;find the file. ;HL buffer pointer was saved. ;copy HL to IX. ;get the file size into HL. ;note BCDE have the start block.</pre>
;				
;				
;				
	ERROR:			

;interpret and process other errors like bad block here.

;

;						
FILE:	DB	'thisfileA',03	;note the	file type	and the	03.

44

FIND FILE 2

```
JUMP TABLE ADDRESS:
                       FGFF
ENTRY:
            A device
              pointer to file name
       DE
       ΗL
              pointer to user buffer
       Zero flag set means file found
EXIT:
       А
              error code if NZ
       BC DE file start block if found
              directory entry if found
       (HL)
       Hi.
               preserved
```

DESCRIPTION:

This routine is identical to FIND FILE 1 on the previous page with only one exception. It sets the FILE NAME ONLY flag of the file search. Thus a file will be found whether its type is A a H h or any other type. When calling this routine, your FILE NAME POINTER must have a file type because the length of the search string is important.

This routine can be useful prior to making a file (of any type). You may wish to check if the same name exists under another type to avoid conflicts. It can also be useful when loading ENCODED file names which specify their function or use according to the file type. If the user says LOAD FILE JUNK, you can find the file, check the file type, and verify that it is suitable to the desired operation.

EXAMPLES:

This routine finds a file and extracts the file type byte for comparison.

```
LD A,4 ;use disk 1.

LD DE,FILE;point to the file name.

LD HL, BUFFER ;store the entry here.

CALL FCFF ;find the file.

JR NZ, ERROR
```

;

;since we know the file name was correctly parsed, we need no safety valve

;

```
A,03
                ; find. the end of name.
LD
        ВC
                ; save start block.
PUSH
                ;look a long way.
LD
        в,1
CPIR
POP
        ВC
                ; get back start block.
DEC
        ΗL
                ;now points to the 03.
```

DEC	ΗL		;now	points	to	fil	e	type	•	
LD	A,	(HL)		;her	e i	t.	is	now	check	it.

;-----

ERROR:

;-----

FILE:	DB	'thisfileA'	,03	;note	the	file	type	and	the
03.									

FIND FILE IN FCB

JUMP TABLE ADDRESS:		RESS:	FCF0
	ENTRY:	HL	Pointer to file name
EXIT:	B HL others	Zero flag s A file mode i points to F preserved	et means file found error code if non-zero (including not found) or contains FCB number if found if file found ile Control Block if found otherwise preserved

DESCRIPTION:

This routine checks the second and third file control blocks for a match of the user supplied file name. If the file is not found, error code 5 is returned in A with the zero flag reset. If the file is found, the file mode is returned in register B, the FCB number in A, and HL points to the start of the FCB so you can decode the DATA in the file.

EXAMPLES:

LD	HL, FILE ;point to th	ne file name.
CALL	FCF0	;find the file.
JR	NZ, NOTFOUND	;this is the only possible error.

;

;now we have the file mode, the FCB number and a pointer to the FCB

;

;-----

NOTFOUND:

;-----

FILE: DB 'thisfileA',03 ;note the attribute and the 03.

CHECK FILE MODE

JUMP TA	BLE ADDF	RESS:	FCF9
	ENTRY:	HL IX	directory entry pointer to FCB
EXIT:		Zero flag s A others	et mode OK error code if non zero preserved

DESCRIPTION:

This routine examines the file mode in the incoming FCB in IX. If the mode is out of range, error code 17 is returned. The Attributes of the file entry are then checked against the requested mode; If the file is READ PROTECT and the request is READ or WRITE PROTECT for WRITE, error code 20 is returned.

While this routine is called by other EOS routines such as READ, WRITE, DELETE, etc. There may be some occasions where the programmer may wish to perform his own mode check. The calling syntax is also strange. If IX points to a File Control Block, it also points to a file name. So why do I also need it in Hi.?

The File modes are:

0	unused (FCB is available for use)
1	read
2	write
3	update (e.g. change attributes) or Read/Write
4	fill rest of space on medium (MAKE with size of 0

EXAMPLES:

LD	HL, FILE	;point to th	e file name.
CALL	FCFO	;find the fil	le in FCB.
JR	NZ, NOT	FOUND	;this is the only possible error.
PUSH	HL		
POP	IX	;copy to IX	as well.
CALL	FCF9	;check mod	le.
RET	Z	;mode OK.	
CP	17		
JR	Z, BADM	ODE	;mode is not 1 2 3 4.
CP	20		
JR	Z,ILLEGA	L	;mode incompatible with attributes

MAKE FILE

```
JUMP TABLE ADDRESS: FCC9

ENTRY: A device

BC DE file size in bytes

HL pointer to file name

EXIT: Zero flag set means success

A error code if non zero

others preserved
```

DESCRIPTION:

This routine begins by determining the number of K required for the file. If BCDE are zero, then the file will be allocated ALL the remaining space on the medium. This technique is used when you create a file without yet knowing how long it will be. It then calls READ BLOCK(74) to get the. directory and verifies that it is indeed a directory. It then looks through the directory entries to find a HOLE of the right size. If the file length' is zero, then it will scan through until it finds BLOCKS LEFT or runs out of room. At the same time, it calls FIND FILE(43) to make sure the file does not exist. After scanning the entire directory, it checks to see if a suitable file was found. The correct directory block is re-read and the file data is copied to the directory entry. The directory is then re-written to disk via WRITE BLOCK(79).

Note that this routine only creates a directory entry of the size requested. The data is not written to the file.

EXAMPLES:

A,8	;use tape 1.
BC , 0	
DE, 12345	;12,345 bytes in the file.
HL, FILE	;point to name of file.
FCC9 ;make t	he directory entry.
Z,GOOD	
11	
Z,TOOBIG	;file too big (bigger than 67MEG).
6	
Z,EXISTS	;file name exists in directory.
12	
Z,DFULL	;directory is full.
13	
Z,MFULL	;media is full.
	A,8 BC,0 DE,12345 HL,FILE FCC9 ;make t Z,GOOD 11 Z,TOOBIG 6 Z,EXISTS 12 Z,DFULL 13 Z,MFULL

;

;more errors like bad block,. etc.

UPDATE FILE IN DIRECTORY

JUMP TABLE ADDRESS: FCCF ENTRY: A device DE pointer to file name HL address of user File Control Block EXIT: Zero flag set no error A error code if non zero others preserved

DESCRIPTION:

This routine starts by finding the file in the directory; it aborts if it is not, found. It moves 23 bytes (everything except the date) into the directory entry. It then calls WRITE BLOCK(79) to re-write the directory entry.

This routine is used to update a file's attributes, adjust the file size, etc. It is used by CLOSE FILE(53) to update the directory when finished with file. It presumes the file already exists on the selected media.

EXAMPLES:

This routine finds a file, changes the attributes, and rewrites the entry.

```
LD
      A,4
            ;use disk 1.
PUSH
      AF
             ;save device.
      DE,FILE; point to the file name.
LD
PUSH
      DE ;save file name.
      HL, BUFFER ;store the entry here.
LD
      FCCC ; find the file.
CALL
      NZ , ERROR
JR
PUSH HL
            ;HL buffer pointer was saved.
      IX ; copy HL to IX.
POP
SET
      3, (IX+12)
                    ;set the system bit of the file.
POP
      DE
             ;file name.
      AF
POP
             device.
      FCCF
CALL
             ;re write entry
JR
      NZ, ERROR ; let's find out what went wrong.
```

:

;

ERROR:

	AND	127	;strip	acknowledge bit if any.
;	interpr	et error	s here.	
;		1		DCB not found
;		2		Device busy
;		3		Device off line
;		5		File not found
;		22		Device error

OPEN FILE

JUMP TABLE ADDRESS: FCC0

ENTRY: A device B mode HL pointer to file name EXIT: Zero flag set means no error A file number OR error code B file number if no error others preserved

DESCRIPTION:

This routine sets up a File Control Block for the user to access the requested file. It begins by checking the 2 File Control Blocks If both are busy error code 7 is returned in register A. It then tries to find the file in the directory. If the file is found, it calls MODE CHECK(48) to ensure the request can be processed. It then sets the control bytes in the FCB (current block, last block, etc.) so the file is ready to be accessed. It also sets up the buffer associated with the FCB as the position in the file and copies the start block of the file to the current block in the FCB.

At this point, the routine checks if the request is a write; if so the job is done. If the request is read, it sets an internal flag (bit 7 of the mode) only if the file size is 1K. This warns the other file routines not to READ another block from this file. It then calls READ BLOCK(74) to pre read the first block of the file.

This routine has two problems. If the file size is zero, it does not initialize the File Control Block properly and may wreak havoc on the media on write operations. The next problem is that it does not tell you where the raw data from the medium is placed. It presumes that you will call READ FILE(54) or WRITE FILE(56) to perform transfers.

It is very important when opening a file to REMEMBER what the FILE NUMBER is. All other access to the file will be made via the FILE NUMBER. The EOS allows you to have two files- opened simultaneously, although they must be on the same medium. Otherwise, a fourth FCB would be required to hold the directory of the other medium. This may have been an oversight in the design of EOS. At the time, there was only the tape drive to worry about. This means that you can't use exclusively the EOS FILE FUNCTIONS to copy a file from one medium to another without buffering.

EXAMPLES:

LD	HL, FILE	;point to a file name.
LD	A,8	;use tape 1.
LD	B,1	;let's read the file.
CALL	FCC0	;open the file.
JR	NZ, ERROR	;let's see what went wrong.
LD	(FNUM),A	;save the file number for later.

CLOSE FILE

```
JUMP TABLE ADDRESS: FCC3
ENTRY: A File number
EXIT: Zero flag set successful
A error code if non zero
others preserved
```

DESCRIPTION:

This routine is used to close off a file and free up its File Control Block. It begins by checking the validity of the file number (can only be 1 or 2 since there are only 2 File Control Blocks for FILES). If the file number is bad, error code 9 is returned. If a request is made to close a file in an FCB that is empty, error code 9 is also returned. It then checks the WRITTEN BIT in the file mode (40H) to see if it the buffer needs flushing. If so, the buffer is written out via WRITE BLOCK(79). If the WRITE is unsuccessful, the routine aborts without clearing the FCB. This gives you a chance to retry. The last step is a call to UPDATE FILE IN DIRECTORY(50). Regardless of the outcome of this routine, the FCB is marked as empty and errors (if any) reported to the user.

This last step can also lead you into trouble. You could have written several K to a file, the data would be there, but if the directory is not updated, you have no way of finding that information again. If you get a BAD BLOCK/CRC error, the only way of knowing if it was when the buffer was flushed or when the directory was written is by checking if the FCB is closed (perhaps that was the intent).

EXAMPLES:

LD	A, (FNUM)	;get back the file number when opened.
CALL	FCC3	;close it off.
JR	Z,COOD	;no errors.
AND	127	strip acknowledge bit if any.
CP	9	
JR	Z , BADNUM	;file number is bad.
CP	3	
JR	Z,IDLE	;device off line.
CP	24	
JR	Z,BADDIR	;directory fails check bytes.
;etc.		

READ FILE

	JUMP TA	BLE ADDRESS:	FCD2	
ENTRY:	A BC HL	file number number of bytes where to put th	s required ne data	
EXIT:	Zero fl A BC others	ag set means su error code if r number of bytes preserved	ccess non zero actually	transferred

DESCRIPTION:

This routine will read a specified number of bytes form a file which has been OPENED(52). It begins by checking the validity of the file number and that the mode is compatible with the request. If the FCB is on the LAST BLOCK, it checks to see if it can deliver the requested number of bytes from the current position on the buffer. Otherwise, it checks how many bytes are remaining in the current block to fill the request. If there is not, it starts by delivering the last remaining bytes in the buffer and tries to read in the next block of the file. This cycle continues until file end is reached or all the bytes are delivered, making successive calls to READ BLOCK(74). If all bytes cannot be delivered, an end of file error code 10 is returned in A. Other error codes indicate other problems such as bad block, device idle, etc.

You can use this routine to read from 1 to 65535 bytes from the input file. Prior to making the call, be sure you have sufficient buffer space starting at (HL) to accept all the bytes requested. The handy thing about this routine is that it allows you to read in an entire file without knowing it's size. Just ask for a large amount and if error code 10 is returned, BC will tell you the file size in bytes.

EXAMPLES:

LD	HL, FILE	;point to a file name.
LD	A, 8	;use tape 1.
LD	B,l	;let's read the file.
CALL	FCC0	;open the file.
JR	NZ, ERROR	;let's see what went wrong.
LD	(FNUM) ,A	;save the file number for later.

;....more code

LD	A, (FNUM)	;get file number.
LD	BC,20000	;we have room for 20000 bytes.
LD	HL, BUFFER	;starting at this address.
CALL	FCD2 ;read t	hem in.
JR CP	Z , NOTALL 10	

happened?	JR	NZ, ERROR	;this is not an EOF error, what
nappenea.	LD	(FSIZE) ,BC	;save this as the file size.

•

WRITE FILE

	JUMP TA	BLE ADDRI	ESS:	FCD5	
ENTRY:	A BC HL.	file num bytes to pointer	ber write to the	data	
EXIT:	A others	error co preserve	Zero fl. de if n d	ag set means on zero	s success

DESCRIPTION:

This routine is very similar to READ on the previous page except that it writes out the specified number of bytes. It fills up the current block, writes it out if full via WRITE BLOCK(79) If the mode is 3 (read/write) it pre-reads the next block prior to writing additional data. Error handling is similar to READ.

The advantage of this routine is that it lets you write sequentially or randomly to a file. When using random write, you must use FILE MODE 3 when opening the file and pre-read up to the end of the previous record prior to writing out the current one.

EXAMPLES:

This routine opens a file for random read and updates record number 10.

LD	HL, FILE	;point to a file name.
LD	A, 8	;use tape 1.
LD	в,3	;let's read/write the file.
CALL	FCCO	;open the file.
JR	NZ , ERROR	;let's see what went wrong.
LD	(FNUM) ,A	;save the file number for later.
LD	(FNUM) ,A	;save the file number for later.

;more code

LD	E,9;read	9	records.	
----	----------	---	----------	--

MORE:

LD	A, (FNUM)	;get file number.
LD	BC,20	;each record is 20 bytes.
LD	HL,BUFFER	;starting at this address.
CALL	FCD2	;read them in.
JR	NZ, ERROR	;let's see what happened.

DEC	Е	
JR	NZ,MORE	
LD	A, (FNUM)	
LD	BC,20	
LD	HL,NEW	;this is the new data.
CALL	FCD5	;update record 10.
JR	NZ, ERROR	;something went wrong.

TRIM FILE

JUMP TABLE ADDRESS: FCED

ENTRY: A device DE pointer to filename EXIT: Zero flag set means no errors A error code if non zero others preserved

DESCRIPTION:

This routine is used to correctly close a file which was MADE [MAKE FILE](49) with a file length of zero. Initially, all remaining space was allocated to the file. The routine starts by finding the file and placing it in its internal FCB buffer. It compares the reserved size with the used size. If they are the same, the routine exits with no error. It then checks that the file is indeed the last entry in the directory. If it is not, the routine exits without an error; it just does not trim. If all the above conditions are met, the directory entry for the file and for BLOCKS LEFT are adjusted to reflect the USED file size. The directory is updated via a call to WRITE BLOCK(79). The only errors this routine generates are those outside its control such as File Not Found, Missing Media, Bad Block, etc.

Failure to TRIM a file which was made with a file length of 0 will effectively disable the rest of the medium. Since the BLOCKS LEFT will be zero, no more files will be allowed.

EXAMPLES:

INITIALIZE DIRECTORY

```
JUMP TABLE ADDRESS: FCBD

ENTRY: A device

C number of K in directory

DE size of medium (160K, 256K, 320K, etc.)

HL Volume name

EXIT: Zero flag set means no error

A error code if non zero

others preserved
```

DESCRIPTION:

This routine is equipped to correctly initialize a directory of any size on a medium of any size. It starts by filling a 1K buffer with zeros. It then moves in the 4 default directory entries: VOLUME, BOOT, DIRECTORY, and BLOCKS LEFT. It then copies the user supplied name into the volume entry, making sure that the volume name is not longer than 11 characters. If it is longer, it is truncated without an error. It then sets the directory size in the volume entry by adding 80HEX to it and placing it in the attributes byte of the volume name. The volume size is then copied to the volume entry and the directory size to the directory. The number of blocks in the directory are subtracted from the volume size to determine the blocks left and that entry is updated. It then writes out the directory with an indirect call to

WRITE ONE BLOCK(80).

If this routine is carefully used, it can successfully initialize any directory. Unlike SmartBasic's INIT command, this routine does not check if the directory is protected. The only protection against an INIT from this function is a write protect tab.

Also, unlike SmartBasic's INIT, it does NOT put a JUMP TO SMARTWRITER in block zero of the medium. If the INIT disk was previously a bootable medium, you may get undesirable results if the disk is BOOTED.

EXAMPLES:

LD	A,4	;do disk one.
LD	С,З	;give it 3 blocks of directory.
LD	DE,360	;this is a double sided 5 1/4 disk.
LD	HL, NAME	;give it this volume name.
CALL	FCBD	;do it
JR	NZ , ERROR	;what happened?

;

NAME: DB 'Guy's Disk',03

RESET FILE

JUMP TABLE ADDRESS: FCC6 ENTRY: A file number EXIT: Zero flag set means success A error code if non zero others preserved

DESCRIPTION:

This function rewinds a file back to the first byte so it can be read over from the beginning. It begins by checking the validity of the file number and checks if the FCB is indeed in use. Upon failure of either of these conditions reror code 9 is returned. It then checks if the current block has been modified. If so, it is written out via WRITE BLOCK(79). The FCB pointers are reset to the beginning of the file. If the mode is WRITE, the USED FILE SIZE is set to 1. If the mode is READ or READ/WRITE, the first block of the file is pre-read into the FCB buffer.

This function may be handy when TWO PASS work is performed on a file. After reaching the end or a determined point, the file can be rewound without resorting to CLOSE FILE(53) and OPEN FILE(52). While it can be used in conjunction with random access files, it is awkward for this use since the file is always rewound to the start rather than a specific point. One way to handle Random access is to rewind the file, read and ignore x-l records, and finally bring in record x. When a random file is very long, this process can be very time consuming, especially from tape.

The recommended approach for randomly accessing files is to calculate your own offsets and read it directly using READ BLOCK(74) WRITE BLOCK(79). Your program will have to remember what the highest record is and update the directory entry accordingly. Care must be exercised not to over run the maximum file size as allocated in the directory. The safest thing to do is likely to adopt the SmartFiler technique and allow only one data base per medium and have it occupy all the space regardless of the size.

EXAMPLES:

Consult the example in WRITE FILE(56). After the file has been opened and written to. It will be necessary to rewind it to access a smaller record number (e.g. 5):

LD	A, (FNUM)	;get the file number.
CALL	FCC6	;rewind to start.
JR	NZ,ERROR	

;

;now use the same technique shown on page 41

;to pre read records which are ahead of the desired one.

;

GET DATE

JUMP TABLE ADDRESS:FCDB

ENTRY: none EXIT: Zero flag set means success A error code if non zero B day in Binary Coded Decimal C month D year others preserved

DESCRIPTION:

This routine extracts the system date from the EOS. If all 3 date bytes are zero, an error code 4 is returned in register A. Otherwise, registers B C D contain the day, month, and year.

The date is stored in BCD format. This is a combination of hexadecimal and decimal and can more accurately defined as the ASCII representation of the decimal characters of the date. Thus January 28, 1987 would be represented by the following HEX numbers: 28 01 87.

EXAMPLES:

This subroutine gets the date and displays it in decimal on the screen. There are more elegant ways of printing BCD numbers, but this one is easy to follow:

SHOWDATE:

CALL	FCDB	
LD	E,32	;the ASCII value of space.
LD	A,B	
CALL	PRINTD	;print the two digits.
LD	A, C	
CALL	PRINTD	
LD	A,D	;and fall through to FRINTD.

PRINTD:

PUSH	AF	;save character.
AND	FO	;strip the lower bits.
RRCA		
RRCA		
RRCA		
RRCA		;move to lower 4 bits.
OR	E	;add in the ASCII offset.

	CALL	PRINTA	;routine to call print character and check
errors.			
	POP	AF	
	AND	OF	;strip the top bits.
	OR	E	
	CALL	PRINTA	;print the other half.
	LD	A,''	;put a space between.
	CALL	PRINTA	
	RET		

PUT DATE

JUMP TA	ABLE	ADDRESS:	FCD8
ENTRY:	С	B month	day
	D	year	

EXIT: all registers preserved

DESCRIPTION:

This routine updates the system date with the user supplied date. It will not return an error since no device operations or validity checks are performed. See GET DATE on previous page for date formats.

The only time that the EOS uses the system date is when a file is CREATED [MAKE FILE](49). At that time, the system date is written to the file control block of the file. Subsequent actions on a file will not change the system date. Even a call to UPDATE FILE IN DIRECTORY(50) will not change the date. Thus the date in a file entry is intended to reflect the creation date of the file.

If you wish to have your files DATED correctly, you should ask the user for the date, read it from a clock, etc. and then PUT in in the EOS via this function.

EXAMPLES:

Following is a machine language routine which may be used from SmartBasic to PUT the date in the EOS. It presumes that memory addresses 28000 to 28002 contain the day, month, and year in the correct BCD format.

LD HL, 28000 LD B,(HL) INC HL LD C,(HL) INC HL LD D,(HL) CALL FCD8 RET

This routine can be POKED anywhere in available memory; following are the related DECIMAL POKE values.

33 96 109 70 35 78 35 86 205 216 252 201

^^^^

This is 28000; change to reflect a different source address for the data.

DELETE FILE

JUMP TABLE ADDRESS: FCE1 ENTRY: A device HL pointer to file name EXIT: Zero flag set means success A error code if non zero others preserved

DESCRIPTION:

This routine calls FIND FILE(43) to see if the file exists. It then extracts the attributes from the file entry to see if the file is locked (bit 7). If it is, error code 16 is returned. If not, the deleted bit (2) is set and the directory entry re written via UPDATE FILE IN DIRECTORY(50).

The EOS uses its own internal buffers to perform this function. Thus two files can be opened and delete file called without fear of running out of buffers.

EXAMPLES:

	LD	A, 8	;use tape 1.
	LD	HL, NAME	;use this file name.
	CALL	FCE1	;try and delete.
	RET	Z	;it worked.
	CP	16	
	JR	Z,LOCKED	
CP	5		
JR	Z,NOFI	LE	;file not found.
CP	24		
JR	Z,BADD	IR	;medium contained invalid directory.

;etc.

RENAME FILE

```
JUMP TABLE ADDRESS: FCDE

ENTRY: A device

DE old name

HL new name

EXIT: Zero flag set means success

A error code if non zero

others preserved
```

DESCRIPTION:

This routine is used to change a file's name; it will not change the file's attributes. It begins by checking if the NEW NAME exists via FIND FILE(43). If it exists, the routine exits without generating an error!(l)! It then tries to find the old file name. If it is not found, error 5 is returned. The next step is to move 12 bytes of the new name on top of the old name and rewrite the directory via UPDATE FILE IN DIRECTORY(50).

(1)This unfortunate oversight can cause many problems. For example, you may try to rename an "A" file to a" and get a no error condition when nothing was done. It seems this routine initially returned an error but COLECO decided not to generate an error because they expected the FIND FILE routine to generate errors. While this is true with the second find, it is not of the first. PROGRAMMERS BEWARE! You must look for the target file name yourself.

EXAMPLES:

Here is a routine to correctly rename a file.

LD	A,4	;use disk 1.
LD	DE,NEW	;point to the new file name.
LD	HL,BUFFER	;store the entry here.
CALL	FCCC	;find the file.
JR	Z,EXISTS	;then rename must abort.
LD.	A,4	
LD	DE,OLD	
LD	HL,NEW	
CALL	FCDE	;now we can try to rename.
RET	Z	;yes we got it.

;

;process errors here

FIND PCB

JUMP TABLE ADDRESS: FC5A ENTRY: none EXIT: IY current PCB address others preserved

DESCRIPTION:

This simple routine just returns the address of the current Processor Control Block. It is the header to the Device Control Blocks which follow immediately after it. The first byte of the PCB (IY+0) indicates its status. The lower 7 bits are usually a 2, indicating it is busy... it is always busy. The top bit is set to indicate it has acknowledged the last command it has received. The next 2 bytes contain a pointer to the PCB itself. While this may seem redundant, it is essential to the proper operation of a RELOCATE PCB(17) command.

Byte 3 (IY+3) may be of interest. It indicates how many devices were FOUND when the net was scanned. Remember that the keyboard and ADAM printer are one device each. The tape drives 1 and 2 only count as 1 device since they share the same processor. Thus, a BASE ADAM will respond with three devices. An ADAM with two disk drives will have 5 devices. A maximum of 15 devices can be handled by the PCB.

EXAMPLES:

FIND DCB

JUMP	TABLE	ADDRESS:	FC54 or FC57
ENTRY	: A	device	
EXIT:	IY	Zero fl A pointer others	ag set means no error device ID or error code to DCB for selected device or garbage if error preserved

DESCRIPTION:

This routine is called internally by various device routines. It returns a pointer to the Device Control Block in register IY. If the user wishes to write his own device handling routines, this one will be the backbone of all operations Unless the NET is re-scanned, it is not necessary to FIND the DCB before every operation. EOS device routines can be speeded up by making your own table of DEVICES and accessing them directly. The EOS originally had two different routines for finding DCB's. While one has been eliminated, its jump table entry points to the active routine.

See DEVICE CONTROL BLOCK STRUCTURE(119) for details of the DCB commands.

EXAMPLES:

The following routine sets up a table for 15 devices and writes their DCB address (or zero) in the table:

LD	в,15								
LD	HL,TABLE+31	;point	to	the	top	of	the	device	table.

FIND:

	LD	А,В
	CALL	FC54
	LD	DE,0 ;prepare to write a zero if none.
	JR	NZ,NODCB
	PUSH	IY
	POP	DE copy DCB address to DE.
NODCB:		
	LD	(HL) ,D;write address to table.
	DEC	HL
	LD	(HL) ,E ;remember we are working backwards.
	DEC	HL
	DJNZ	FIND

REQUEST DEVICE STATUS

```
JUMP TABLE ADDRESS: FC7E
ETTRY: A device
EXIT: Zero flag set means no errors
A error code if non-zero
IY DCB address or garbage if DCB not found.
others preserved
```

DESCRIPTION:

This routine finds the DCB(67) for the requested device. It asks the device for status and waits for a reply. When the DCB replies, the status is compared with 80HEX and control is returned to the user with IY pointing to the DCB.

This routine returns the status of the DCB itself. For the status of the device, see the routine on the next page.

EXAMPLES:

LD	A,4	;check disk 1.
CALL	FC7E	;how is it doing?
RET	Z	;everything is fine.
AND	7 F	;strip the high bit.
CP	1	
JR	Z,NODCB	;sorry no disk one.
CP	2	
JR	Z,BUSY	;leave me alone I am working.
CP	3	
JR	Z,IDLE	;device off line.

;etc.

GET DEVICE STATUS

```
JUMP TABLE ADDRESS: FCE4
ENTRY: A device
EXIT: Zero flag set means no errors
A error code if non-zero or status
others preserved
```

DESCRIPTION:

This routine gets the device specific status which was reported during the REQUEST FOR STATUS on the previous page. In order to get a complete status report, both these routines should be called and evaluated.

The routine does not perform a STATUS request, it just reads the DEVICE STATUS FLAG from the device control block. This is a complex bit pattern indicating presence of an alternate device and whether or not media is present. These bit patterns are placed in the upper and lower nibble of the status which is returned in A. If you are checking a PRIMARY device (one with a number from I to 15), you should check the lower nibble. If you are checking a secondary device (one with a number from 17 to 31), you should check the upper nibble.

```
The bit pattern is as follows: 0000 unknown error/or all OK
0001 CRC Error
0010 Missing Block
0011 Missing Media
0100 Missing Drive
0101 Write protect tab in place
0111 Drive Error
```

EXAMPLES:

The following routine asks for the device status flag. the device status of the tape drives and reads

LD CAI	A,8 .L FC7E	;ask about tape 1. ;get status first.
JR	NZ, ERROR	;problem with device.
LD	A, 8	
CAI	L FCE4	;ask for device status.
AND) 0 F	;use lower nibble only.
CP	4	
JR	Z , NODEVICE	;there is no tape 1.
CP	3	
JR	Z,NOMEDIA	;no tape in the drive.
LD	A,18H	
CAI	L FCE4	;ask about tape 2.
AND	F0	;strip low bits this time.
RRC	A	
RRC	CA	

RRCA	
RRCA	;shift high to low.

;now process as above for tape 2 status.

SOFT RESET DEVICE

```
JUMP TABLE ADDRESS: FC90
ENTRY: A device
EXIT: Zero flag set means success
A error code if non zero or 128 if complete
others preserved
```

DESCRIPTION:

This routine can be used to reset a device to its default inactive state. While there are routines to specifically reset the keyboard and printer, they both call this routine. Other devices like the tape and disk drives, must be reset from this routine.

The routine begins by finding the DCB for the device; it returns an error if not found. It then checks if the device is busy; a busy device is not reset as this may interrupt a crucial activity like writing a block to disk. The next step is to ask the DCB to RESET the device. The routine then waits for the DCB to acknowledge the command and compares the result with 128 which is the OK status. Thus, if there are any problems, a NON ZERO flag is returned to the user for interpretation.

EXAMPLES:

LD	A, 8	;reset tape 1.
CALL	RESET	;do it.

;

;more code

;subroutine to reset the device in A

;

RESET:

CALL	FC90	
RET	Z	;reset went OK
AND	127	;strip acknowledge bit.
CP	3	
JR	Z,BUSY	;device is doing something
CP	1	
JR	NZ,NODCB	;sorry I don't have a device.

SOFT RESET KEYBOARD

```
JUMP TABLE ADDRESS: FC93
ENTRY: none
EXIT: Zero flag set if success
A error code if non zero
others preserved
```

DESCRIPTION:

This routine simply loads the keyboard device(l) and jumps to SOFT RESET DEVICE(71). It has one important function...take off the SHIFT LOCK key. Sometimes, your program may expect a lower-case character or a number from the keyboard. If the KEY PRESS is not echoed to the screen, you may receive a \$ instead of a 4, reject it, and the user is wondering what happened. Sending a SOFT RESET to the keyboard, makes sure that the LOCK key is released.

EXAMPLES:
DEVICE OPERATIONS

SOFT RESET PRINTER

```
JUMP TABLE ADDRESS: FC96
ENTRY: none
EXIT: Zero flag set means success
A error code if non-zero
others preserved
```

DESCRIPTION:

This routine also loads the PRINTER device number(2) and jumps to SOFT RESET DEVICE(71). As with the keyboard reset, it accomplishes a useful function. When the printer receives a reset, it returns the print head to the left margin and returns the printer to FORWARD MOTION. This function is highly recommended before any printing job. If the last job was aborted in mid stream, you want to make sure you are not left hanging in the middle of a line.

Note that the printer will not be reset if it is busy (printing something). You should make sure it is not busy by performing a status check first.

READ BLOCK

JUMP TA	BLE ADDR	ESS: FCF3
ENTRY:	A BCDE HL	device block number destination for data
EXIT:	A others	Zero flag set means success error code if non zero preserved

DESCRIPTION:

This is the most intensive READ BLOCK routine. It begins by calling READ ONE BLOCK(75). If an error other than TIMEOUT is returned, it retries up to twice to complete the request. if the command is not accepted, then a media error is returned (22). If the command is accepted or a timeout, it CALLS REQUEST DEVICE STATUS(68) until the time out clears or an error is returned. It then gets the MEDIA status (upper or lower nibble) to check for errors. If the media or the device is missing, then error code 22 is returned. If there is no media error, a second READ request is sent. After two retries, the command aborts.

While this routine catches a variety of errors, it almost always returns the same error code 22. It may be difficult for the program to interpret the errors generated by the routine. If you just want to tell the user there is an error, then use this routine since it should catch all the possibilities. If you want to decode the errors yourself, use the one on the next page.

Note that the retries in this routine do little good since a tape or disk error is not cleared by the controller until the drive door is opened and the media "adjusted".

Note also that the second read request does not really slow down the operation since the tape and disk drives have a 1K memory buffer and can instantly return the data if the block number is the same.

COLECO had anticipated VERY LARGE media when it designed the READ BLOCK routines. Accordingly, you must send a quadruple precision number as the BLOCK to read. Register BC contains the HIGH BLOCK NUMBER (usually zero), and register DE, the LOW BLOCK NUMBER (up to 65535K). When we have devices on the ADAM NET which have more than 64MEG of storage, then we will start using BC.

LD	A, 4	;read disk one.
LD	BC,0	
LD	DE,100	;read block 100.
LD	HL, 12345	;put the data here.
CALL	FCF3	;try and read.
JR	NZ, ERROR	;guess we got an error code 22.

READ ONE BLOCK

JUMP :	TABLE A	ADDRESS:	FC69		
ENTRY	: A BCDE HL	device block nu RAM addr	mber ess to put	data	
EXIT:	A othe	error co rs preserve	Zero flag se de if non z d	et means ero	success

DESCRIPTION:

This routine is quite simple compared to READ BLOCK on the previous page. It calls START READ ONE BLOCK(76) and aborts on error. It then CALLS END READ ONE BLOCK(77) until the request is completed or an error returned.

This routine will return an error if the DCB is not found or if the device is busy doing something else. It will also return an error if the device is off line (idle) or if the device itself returns an error. While not as elegant as READ BLOCK, it gives the programmer the opportunity to check for other errors.

EXAMPLES:

This routine tries to read one block. If the returned error is not BUSY or NO DCB, the programmer checks if media is missing. Then the appropriate action can be taken.

LD	A,4	;read disk one.
LD	BC,0	
LD	DE,100	;read block 100.
LD	HL,12345	;put the data here.
CALL	FC69	;try and read.
JR	Z,GOOD	
AND	127	;strip the acknowledge bit if any.
CP	1	
JR	Z,NODCB	;oops.
CP	2	
JR	Z,BUSY	;device is busy on something else.
CP	3	
JR	Z,IDLE	;device is off line.
LD	A,4	
CALL	FCE4	;ask for device status.
AND	OF	;use lower nibble only.
CP	4	
JR	Z,NODEVICE	;there is no disk 1.
OR	A	
JR	NZ,NOMEDIA	;no disk in the drive.

START READ ONE BLOCK

JUMP TA	BLE ADDF	RESS: FCA2
ENTRY:	A	device
	BCDE	block number
	HL	RAM address to put data
EXIT:	Zero fl	ag set means success
	Δ	error code if non zero
	others	preserved (including A if no error)

DESCRIPTION:

This routine starts by calling FIND DCB(67) and aborts if there is an error. It then checks if the device is off line (idle). It then writes the pertinent data into the DCB and issues a READ request. Control is then returned to the user so the device (tape or disk) can do its work while other activities are in progress.

Have you ever noticed that the SUPER GAME Buck Rogers goes to the disk or data pack WHILE THE GAME IS IN PROGRESS? It does that using START READ and END READ on the next page. The reason for this is to load the NEXT SCREEN so it is instantly ready for use after finishing this screen. Unless you are extremely good, you never have to wait after finishing a screen. This process known as background loading can be quite effective when properly used.

The effective transfer rate of the DATA drives is 1400 bytes per second. Thus, it takes close to a second to READ a block after the correct place has been found. During that period of time, hundreds of operations may be performed by the Z-80 if there is no need to WAIT for the data.

EXAMPLES:

See END read for a complete example.

END READ ONE BLOCK

JUMP TABLE 2	ADDRESS:	FC45
ENTRY:	А	device
EXIT:	Carry f Zero fl A others	lag set means complete ag set means no error if CARRY error code if non zero preserved

DESCRIPTION:

This routine starts by finding the DCB(67) and returns an error if not found. It then checks if the device is off line (idle). It then checks if the DCB has acknowledged the command (start read). If not, the CARRY FLAG is reset (no carry) and control returned to the caller. If the command has been acknowledged, the status is compared to 80HEX, the carry flag set, and control returned to the caller.

It is important to check the CARRY flag first. If it is not set, then don't presume there is an error. If the Carry is set and a NON zero condition exists, then there was an error. In order to decode the error, start by subtracting 80HEX and comparing to the DCB error code table (92).

EXAMPLES:

These excerpts show a potential game situation which uses background loading of ONE block from disk. It calls several subroutines which are not detailed but can be used as a general guide for such uses:

LD	A,4	;use disk 1.
LD	BC,0	
LD	DE,17	;get from block 17.
LD	HL, 12345	;put it here.
CALL	FCA2	;start read.
JP	NZ, ERROR	;oops.

WAIT:

CALL	READJOY	;read the joystick.
CALL	MOVE	;move player if requested.
CALL	FIRE	;execute fire button if any.
CALL	UPDATE	;move monsters, obstacles, etc.
LD	A,4	
CALL	FC45	;are we done?
JR	NC ,WAIT	;command not acknowledged yet.
JP	Z,DONE	;background loading completed.
AND	127	;strip acknowledge bit.
CP	1	
JR	Z,NODCB	

CP	2		
JR	Z,BUSY		
CP	3		
JR	Z,IDLE		

WRITE BLOCK

JUMP TA	BLE ADDR	ESS:	FCF6	
ENTRY:	A BCDE HL	device block where	number to write	e data
EXIT:	Zero fl A others	ag set error preser	means s code if ved	uccess non zero

DESCRIPTION:

This is the intensive WRITE BLOCK routine. It begins by calling WRITE ONE BLOCK(80). If an error other than TIMEOUT is returned, it retries up to twice to complete the request. if the command is not accepted, then a media error is returned (22). If the command is accepted or a timeout, it CALLS REQUEST DEVICE STATUS(68) until the time out clears or an error is returned. It then gets the MEDIA status (upper or lower nibble) to check for errors. If the media or the device is missing, - then error code 22 is returned.

While this routine catches a variety of errors, it almost always returns the same error code 22. It may be difficult for the program to interpret the errors generated by the routine. If you just want to tell the user there is an error, then use this routine since it should catch all the possibilities. If you want to decode the errors yourself, use the one on the next page.

Note that the retries in this routine do little good since a tape or disk error is not cleared by the controller until the drive door is opened and the media "adjusted".

Contrary to READ BLOCK(56), this routine does not ask for a second write as it would require rewinding the tape and writing again. This operation would be quite slow.

LD	A, 24	;write to tape 2.
LD	BC,0	
LD	DE,100	;write block 100.
LD	HL, 12345	;put the data found here.
CALL	FCF3	;try and write.
JR	NZ, ERROR	;guess we got an error code 22.

WRITE ONE BLOCK

JUMP TA	BLE ADDR	RESS:	FCB4				
ENTRY:	A BCDE HL	device block n [.] memory	umber address	to s	start	writing	from
EXIT:	Zero fl A others	ag set m error c preserv	neans su ode if r ed	cces non :	s zero		

DESCRIPTION:

This routine calls START WRITE ONE BLOCK(81) and returns if there is an error. It then repeatedly calls END WRITE ONE BLOCK(82) until such time as the command is completed. When the acknowledge is received, the end write error, if any, is returned to the caller. The routine stays in total control until the process is completed or an error generated.

EXAMPLES:

This routine tries to write one block. If the returned error is not BUSY or NO DCB, the programmer checks if media is missing. Then the appropriate action can be taken.

LD	A,4	;write to disk one.
LD	BC,0	
LD	DE,100	;write block 100.
LD	HL,12345	;put the data found here.
CALL	FG69	;try and write.
JR	Z,GOOD	
AND	127	;strip the acknowledge bit if any.
CP	1	
JR	Z,NODCB	;oops.
CP	2	
JR	Z,BUSY	;device is busy on something else.
CP	3	
JR	Z,IDLE	;device is off line.
LD	A,4	
CALL	FCE4	;ask for device status.
AND	OF	;use lower nibble only.
CF	4	
JR	Z,NODEVICE	;there is no disk 1.
OR	A	
JR	NZ,NOMEDIA	;no disk in the drive.

START WRITE ONE BLOCK

JUMP TABLE ADDRESS: FCAB ENTRY: A device BCDE block number HL RAM address to start writing from EXIT: Zero flag set means success A error code if non zero others preserved (including A if no error).

DESCRIPTION:

This routine starts by calling FIND DCB(67) and aborts if there is an error. It then checks if the device is off line (idle). It then writes the pertinent data into the DCB and issues a WRITE request. Control is then returned to the user so the device (tape or disk) can do its work while other activities are in progress.

Except for the WRITE request, this routine is identical to START READ ONE BLOCK(76).

END WRITE ONE BLOCK

JUMP TABLE ADDRESS: FC4E

ENTRY: A device

EXIT: Carry flag set means complete Zero flag set means no error if CARRY A error code if non zero others preserved

DESCRIPTION:

This routine starts by finding the DCB(67) and returns an error if not found. It then checks if the device is off line (idle). It then checks if the DCB has acknowledged the command (start write). If not, the CARRY FLAG is reset (no carry) and control returned to the caller. If the command has been acknowledged, the status is compared to 80HEX, the carry flag set, and control returned to the caller.

This routine is identical to END READ ONE BLOCK(77). See that routine for more details. As a matter of fact, either END READ or END WRITE may be called to determine if a device is done its operation whether read or write.

SET VDP PORTS

JUMP TABLE ADDRESS: FD11 ENTRY: none EXIT: A current memory configuration BC destroyed DE preserved HL destroyed

DESCRIPTION:

This routine starts by remembering what the current memory configuration is. It then calls bank switch [SWITCH MEMORY BANKS](20) to switch in the 0S7. This is the mini operating system used by SmartWriter. It extracts the port addresses for the VDP, Games Controllers, Strobe and Sound ports. Finally, it restores the default memory configuration.

As a byproduct, this routine returns the current memory configuration. This may be handy to make sure the settings are correct for the desired operation.

While this routine is called by the EOS cold start [INITIALIZE EOS](11), there may be situations where the programmer may need to refresh the EOS data areas where the default control ports are stored.

While it is not essential to know what the port numbers are, following are the memory locations and port values for EOS 6. The addresses may be different in other revisions of EOS but the port values should be the same.

PORT	ADDRESS	VALUE	
VDP Control	FC29	191	
VDP Data	FC2A	190	
Joystick 0	FC2B	252	
Joystick 1	FC2C	255	IN ONLY
Strobe set	FC2D	128	
Strobe reset	FC2E	192	
Sound	FC2F	255	OUT ONLY

INITIALIZE VRAM TABLES

JUMP TAE	BLE ADDR	ESS:	FD2	9								
ENTRY:	HL	A table	addres	t ss	able	number						
EXIT:			all	regis	sters	, includi	ng IX	and	IY	are	used	

DESCRIPTION:

This is a very useful routine which can be used to set up any of the 5 VDP tables. While the routine correctly sets up the pointers to the tables, it does not check if the tables overlap each other. It is up to the programmer to ensure correct setting of the VDP tables. Once the tables are set up, subsequent EOS calls involving characters, patterns or sprites will be sent to the VDP according to the tables defined here.

The EOS cold start routine [INITIALIZE EOS](11) does NOT set up the VDP; you must set up your own tables. It is essential to set up EACH table which will be used. In order to facilitate the calculation of tables, the routine asks for a value in HL which is the VDP address where the table should start. The routine takes care of the encoding of the data.

TABLE NUMBER	NAME	SIZE
0	Sprite Attribute	128 bytes
1	Sprite Pattern	256 bytes
2	Pattern name table	varies with VDP mode
3	Pattern Generator	2048 bytes
4	Pattern Color	varies with VDP mode

EXAMPLES:

This routine shows the requirements for 32 column displays. VDP memory area from 420 Hex to 7FF Hex is unused. Neither is the area form 1000 Hex to 37FF Hex. All area above 3980 Hex is also available. This configuration leaves plenty of room for bigger pattern and color tables for the other VDP modes.

LOAD DEFAULT ASCII IN VDP

JUMP TABLE ADD	RESS:	FD38
ENTRY:	A	none
EXIT:		All registers including IX are used.

DESCRIPTION:

This routine gets the address of the pattern generator table as it was set up using INIT TABLES on the previous page. It then asks PUT ASCII on the next page, to place the first 128 characters in the start of the table. This routine is a handy way of bringing in all the ASCII characters without calculating the offsets.

The user MUST call this routine before printing any characters to the screen unless the screen was already initialized by another program.

put ASCII IN VDP

JUMP TABLE ADDRESS: FD17

ENTRY: BC number of characters (not bytes) DE address in Video RAM to start at HL character number to start at

EXIT: all registers used except IY

DESCRIPTION:

This routine copies a specific number of ASCII characters into VRAM. It begins by multiplying HL by 8 to get the offset position in the table. It also multiplies BC by 8 to get the total byte count. It then switches in the EOS ROM where the default ASCII characters are located. It gets the address of the ASCII character set and adds the offset to the first character. It then calls WRITE VRAM(88) to move the data. The last step is to restore the memory configuration to its previous state. When calling this routine, it is essential to indicate the proper offset into video RAM based on the tables which were set up using the routine on page 65.

EXAMPLES:

This subroutine restores one ASCII character (sent in A) to its default state. It gets the base VAAM address from memory where the programmer stored it when initializing the VDP. It might be used if a character was intentionally (or accidentally) altered for a special effect.

LD	BC,1	;restore only one.
LD	DE, (PATTERN)	;base address of pattern table.
LD	н,О	
LD	L,A	;the pattern to restore.
ADD	HL,HL	
ADD	HL,HL	
ADD	HL,HL	;times 8-offset.
ADD	HL,DE	
ΕX	DE,HL	;here's where to start in table.
LD	н,О	
LD	L,A	;put pattern number back in HL.
CALL	FD17	;do it.

If you are going to make significant use of this routine, it is wise to set your pattern table at 0. In that case you only need to multiply the character by 8 to determine the offset:

LD	BC , 1
LD	н,О
LD	L,A
ADD	HL,HL
ADD	HL,HL
ADD	HL,HL
ΕX	DE,HL

LD	н,О		
LD	L,A		
CALL	FD17	;much	shorter.

WRITE VRAM

JUMP TABLE ADDRESS: FD1A ENTRY: BC number of bytes to write DE VRAM start address HL where to get data (user buffer) EXIT: HL points one past end of data moved others destroyed

DESCRIPTION:

The routine starts by preparing the VDP for a write operation by feeding it the start address in DE. It then sends the bytes one at a time through the VDP data port. Since the port does not return any errors, the routine just presumes all went well and exits after sending the last byte.

EXAMPLES:

This routine sends a screen full of text to the name table. This can be a quick way to POP information into the screen (e.g. a window).

LD	BC ,768	;get a screen full worth of 32 column data.
LD	DE, (NAME)	;where did I put the name table?
LD	HL, SCREEN1	;this is the screen I want displayed.
CALL	FD1A	

READ VRAM

JUMP TABLE ADDRESS: FD1D
ENTRY: BC number of bytes to read
DE VRAM start address
HL where to put data (user buffer)
EXIT: HL points one past end of data moved
others destroyed

DESCRIPTION:

This routine is the logical complement to WRITE VRAM on the previous page. It collects the specified number of bytes from the VDP and places them in the where they can be analyzed, modified, and perhaps sent back user's RAM area to the VDP.

PUT VRAM

```
JUMP TABLE ADDRESS:
                      FD2C
              table number
ENTRY: A
       DE
              first entry to update
              pointer to user buffer
       HL
              number of entries to move
       ΙY
EXIT:
       ΗL
              points to one past end of data moved
       IX
              preserved
       others destroyed
```

DESCRIPTION:

This routine is more user friendly than WRITE VRAM(88). It takes care of all the arithmetic for you. All you need to do is specify which table you wish to update and let the EOS take care of offsets, table addresses, etc.

The routine checks which table to update (see list on page 65) and multiplies the entry numbers, offsets, etc. by 4 or 8 depending if sprite attributes or pattern tables. It then extracts the base VRAM address from its tables and adds in the offset to the start of the table. The last step is to call WRITE VRAM to actually move the data.

EXAMPLES:

This routine updates the sprite attributes for sprite numbers 10 to 19

```
LD A,0
LD DE,10
LD HL, SP+10*4
LD IY, 10
CALL FD2C
```

;do sprite attributes. ;start at sprite 10. ;start 40 bytes in the sprite table. ;update 10 entries.

This routine sends one full line of text to line 10

LD	A,2	;use the name table.
LD	DE,320	;start at line 10 (32 per line).
LD	HL, LINE	;move in this line.
LD	IY, 32	;move 32 entries.
CALL	FD2C	

GET VRAM

```
JUMP TABLE ADDRESS:
                      FD2F
              table number
ENTRY: A
       DE
              first entry to get
              pointer to user buffer
       HL
              number of entries to move
       ΙY
EXIT:
       ΗL
              points to one past end of data moved
       IX
              preserved
       others destroyed
```

DESCRIPTION:

This routine is the complement of PUT VRAM on the previous page. It extracts from VRAM a specified number of entries from the desired table. See additional explanations on previous page.

EXAMPLES:

This routine gets a full line of text from line 10 and shifts all the characters right by one. It then writes the data back; the last character on the right disappears.

LD A,2 ;use name table. DE,320 ;start at line 10. LD LD HL,LINE ; move it to here. LD IY, 32 ;move 32 entries. FD2F ;get it here. CALL LD A,2 ; use the name table. DE,320 ;start at line 10 (32 per line). LD HL, LINE - 1 ;start one behind it. LD (HL),' ' LD ;put a space there. LD IY, 32 ;move 32 entries. CALL FD2C ;scroll the line over.

WRITE VDP REGISTER

JUMP TABLE ADDRESS: FD20 ENTRY: B Register to write to C Data to send EXIT: ABCDE destroyed others preserved

DESCRIPTION:

This routine extracts the VDP control port address from the EOS table, sends the DATA out the port and then sends the register number to which 128 has been added. If VDP register 0 or 1 is being written to, the data is stored so it knows what mode it is in when calculating tables. Writing to the VDP registers is the way to set up various VDP modes. Following is a breakdown of the VDP values; only the pertinent bits are shown, the others are zero.

REGISTER O	BIT 1	Meaning if set Graphics mode 2	
1	7 6 5 4 3 1 0	Always 1 0 to blank display, 1 Non Maskable Interrupt TEXT mode on (40 colum MULTI COLOR mode on 16x16 sprite enable double size sprite ena	to activate enable m) \ set only one of these bits / or none for 32 column ble
2 3 4 S Attributes 6 Pattern	3210	multiplied by 400 multiplied by 40 multiplied by 800 multiplied by 80 multiplied by 800	HEX is address of NAME table HEX is address of COLOUR table HEX is address of PATTERN table HEX is address of SPRITE HEX is address of SPRITE
7	7654 3210	TEXT color in BORDER color	TEXT mode (40 column)

Bit 6 of register 1 can be cleared (off) while a screen is being PAINTED. The screen will be blanked but drawing will still take place. Setting Bit 6 will instantly TURN ON the entire screen... nice special effect.

Bits 0 and 1 of register 1 are not the same. Bit 1 uses 4 consecutive sprites (e.g. 0,1,2,3 to make a composite sprite). Bit 0 doubles the size of each bit to make a double sized sprite. Both bits can be combined for 32x32.

Registers 2 to 6 are handled automatically by INITIALIZE VRAM TABLES (84).

The TEXT mode uses no color table. SET (on) bits are the color specified by register 7. CLEAR (off) bits are always transparent and allow the border color (register 7) to shine through and become the background. The same is true of the 32 column mode when the CLEAR bits are set to transparent.

READ VDP REGISTER

JUMP T	ABLE ADD	RESS: FD23
ENTRY:	none	
EXIT.	Δ	VDP control value
LATT.	C	Control port number
	-	others preserved
		-

DESCRIPTION:

This routine reads in whatever value resides in the VDP control port, stores it internally, and returns the control value in A to the caller.

The VDP CONTROL port is also referred to as register 7 which is READ ONLY. Note that the registers on the previous page are WRITE ONLY. If you need to remember what you wrote to the registers, store it yourself. Reading the CONTROL port provides 4 items of data in the bit pattern:

bit 7	set on each raster scan (interrupt)
bit 6	set if 5 sprites on the same line
bit 5	set if two sprites overlap
bits 43210	fifth sprite if any.

Reading the CONTROL PORT clears any collisions or 5th sprites which were recorded. If more than one condition requires verification, be sure sand save the output value as it cannot be retrieved again. The sprite overlap (collision) flag does not tell you which two have collided, but it is an easy way to check if there is a collision. If no collision, then you can skip ahead. If there is one, then check each pair to determine who has collided with whom.

Have you noticed on some arcade games that some of the objects (sprites) flicker at times? When this happens, have a close look: there are 5 or more sprites on the same line. BURGER TIME is a good example. In order for the sprite not to totally disappear, programmers remove one of the higher priority sprites allowing the fifth sprite to show. They then replace the other sprite making the 5th disappear again. It can be a lot of work but 'keeps the sprites visible.

FILL VRAM

```
JUMP TABLE ADDRESS: FD26
ENTRY: A value to write
DE repeat count
HL address to write to
EXIT: All registers destroyed except IX IY
```

DESCRIPTION:

This routine sets up the VDP for a write operation to address HL. It then sends the byte in A to VRAM DE times. When used to fill the name table, it puts the same character throughout the specified area.

EXAMPLES:

This routine sets up the name table and fills 24 lines of 32 rows with a space. This clears the screen the hard way.

HL,0 ;use start of VRAM. LD LD A,2 ; for the name table. FD29 ;WRITE VDP register CALL LD A , ;put a space. DE,24*32 LD ; in the whole screen. HL,0 ;starting at beginning. LD CALL FD26

CALCULATE PATTERN POSITION

```
JUMP TABLE ADDRESS: FD32
ENTRY: D Y position
E X position
EXIT: DE absolute offset
others preserved
```

DESCRIPTION:

This routine takes the drudgery out of figuring the proper offset related to a given set of X Y coordinates. It simply multiplies Y by 32 and adds X. Unfortunately, the routine is set up for a 32 column screen configuration. If you are using a 40 column set up, you are on your own. Once the offset is calculated, you can use PUT VRAM(70) to write data directly to a screen position without affecting the current cursor position. If you wish to position the cursor, you should use the control sequences in CONSOLE DISPLAY SPECIAL(23).

The routine is equipped to handle negative x,y coordinates but I have no idea why you would want to use them.

EXAMPLES:

This routine writes a message to a particular location on the screen.

LD	E,10	;goto line 10.
LD	D,5	;column 5.
CALL	FD32	;get offset.
LD	A,2	;name table.
ΕX	DE,HL	;put first entry into DE.
LD	HL,MESS	SAGE ;print this word.
LD	IY , 11	;it is 11 bytes long.
CALL	FD2C	;put in in VAAM.

•••••

MESSAGE:

DB 'Please Wait'

For 40 columns, following is a routine to calculate 40*y+x in DE

```
Н,О
LD
      L,D
             ;HL-y.
LD
      HL,HL
             ;*2.
ADD
      HL,HL
             *4
ADD
      HL,HL
ADD
             ;*8.
      В,Н
LD
LD
      C,L
             save *8.
      HL,HL ;*16.
ADD
      HL,HL ;*32.
ADD
ADD
      HL,BC ;*40.
LD
       D,0
      HL,DE ;40*y+x.
ADD
```

POINT TO PATTERN POSITION

JUMP TABLE ADDRESS: FD35 ENTRY: DE signed number EXIT: E -DE/8 or 127 or -128 (80 HEX) others preserved

DESCRIPTION:

This routine is used to determine the pattern number for a given offset. Since each pattern is 8 bytes, dividing DE by 8 does the job. The routine can handle negative offset and returns either 7F or 80. Again, I have no idea what the negative offsets are used for.

WRITE SPRITE TABLE

JUMP TABLE ADDRESS: FD3B ENTRY: A number of sprites to write DE Sprite attribute table HL Sprite priority table EXIT: IX preserved IY preserved others destroyed

DESCRIPTION:

This routine writes the specified number of sprites to the VDP in the order specified by the priority table in (HL). This routine is one way to reorder the sprites without having to MOVE all the entries in the table. It can be used to help overcome the 5th sprite priority problem.

EXAMPLES:

This routine uses two priority tables, alternating on each successive call to send the sprites in a different order.

LD	HL,ONE	;maybe use first order.
LD	A, (TOGGLE)	;
NEG		;toggle it.
LD	(TOGGLE) ,A	;save it back.
JR	Z,USE1	;let's use the first table.
LD	HL,TWO	;let's use the alternate.
USE1:		
LD	DE ,ATTRIBUTE	;get the attributes table.
LD	A, 6	;it contains 6 sprites.
CALL	FD3B	;do it.
RET		

••••

ONE:	DB	0,1,2,3,4,5
TWO:	DB	5,4,3,2,1,0

GAME CONTROLLERS

READ GAME CONTROLLER

JUMP TA	BLE ADDF	RESS:	FD3E
ENTRY:		A	controller/spinner value bit 0 controller 0 bit 1 controller 1 bit 7 enable spinner for selected controller
			e.g. use 131 decimal or 83 HEX to read all
		IX	user decode table
EXIT:	IY others	preserve destroye	ed ed

DESCRIPTION:

This routine can read either joystick or both and optionally read their spinners as well. It checks if controller 0 was requested and skips to controller 1 if not. If neither controller is requested, the routine returns immediately. After reading controller 0, it checks if controller 1 was also requested. It then calls a debounce routine which must temporarily disable the interrupts while reading the joystick(s). It then gets the spinner count and resets it to zero. It then reads and decodes the fire buttons, keypad, and joystick data. If any of the data is the same as the last time it is placed in the user buffer. Thus, it takes two successive calls with identical data to register data and effect a debounce. If the spinner was enabled, the spinner count is added to the previous spinner value in the user's table.

The user's table is ordered in this fashion:

0	Joystick 0	KEYPAD	VALUE	ES	JOYSTICK
1	Right Fire button 0	1	2	3	1
2	Left Fire button 0	4	5	6	9 3
3	Keypad value O	7	8	9	\land \mid /
4	Spinner O	10	0	11	82
5	Joystick 1				/ \
6	Right Fire button 1	12 purp	ole bu	utton (*3)	12 6
7	Left Fire button 1	13 blue	e butt	con (#3)	4
8	Keypad value 1 15 blue	and pu	rple		
9	Spinner I	15 no }	key pi	ressed	0
	is off				

Note that the EOS has an error in decoding the blue/purple button combination. In EOS 6, you can change byte E205 to 14 to return the correct data when those buttons are pressed together.

LD	A,3 ;read both.
LD	IX,TABLE ;put data here.
CALL	FD3E
LD	IX,TABLE ;restore pointer.
LD	A, (IX+1) ;get right button.
OR	(IX+2) ;OR with left button.
JR	NZ, PUSHED ; at lest one button pushed.

GAME CONTROLLERS

UPDATE SPINNER

JUMP TABLE ADDRESS: FD41 ENTRY: none EXIT: DE preserved IX preserved IY preserved others destroyed

DESCRIPTION:

This routine checks the spinner value in both joysticks and increments or decrements the internal spin table if either was active. The next time that READ GAME CONTROLLER(100) is called, the spinner's incremented value will be added to the previous value in the user table - IF AND ONLY IF the spinner bit was enabled when the call was made.

One spinner is the roller controller, when set in Roller Controller mode of operation. Unfortunately, the spinner spins so fast that you must call this routine very frequently in order to CATCH most of the spinner action. It seems the spinner can interrupt the Z-80 and branch to 38H. Thus, you should be able to set up an interrupt at 38H which branches to FD4l. In this way, you would be able to update spinner values at a fast rate and interpret the spinner update when you call READ GAME CONTROLLER. Unfortunately, I have not had any success in setting up an interrupt handling routine.

EXAMPLES:

This routine uses SmartBasic's PDL routines as a vehicle for reading and updating the spinner. There is no PDL function to return the SPINNER value, so it is necessary to PEEK directly into the joystick table. Unfortunately, BASIC reads the spinner at the wrong place and it is necessary to FIX its calling convention. Each time you CALL READ J0YSTICK (PDL in BASIC), the EOS spinner value is extracted and cleared. It is sent to the USER only if requested. This allows you to CLEAR the current SPINNER update by CALLING READ J0YSTICK with the SPINNER bit off.

100 POKE 26914, 3:POKE 26929, 3:REM turn off SPINNER read at wrong place

110 POKE 27115, 131:REM turn SPINNER read at correct place

115 p=PDL(0):REM read any joystick

120 PRINT PEEK(16787), PEEK(16782), CHR\$(128):REM this is the new spinner

121 FOR x=1 TO 1000:CALL 64833:NEXT:REM make several CALLS to UPDATE spinner

122 PRINT " "; PEEK(65112), PEEK(65113),:REM this is update since last time

130 GOTO 115:REM keep on repeating until ^C

SOUND ROUTINES

SOUND INITIALIZATION

JUMP TABLE ADDRESS: FD50 ENTRY: B number of entries to create HL pointer to list EXIT: all registers used

DESCRIPTION:

This routine sets up an internal pointer to the user's list of songs, or special effects. It then sets up the pointer to each of the 4 voices to an END-OF-SONG so they will all be synchronized when START SOUND(105) is called. The routine then falls through to SOUND OFF on the next page.

Sound CONTROL data is in coded binary format, with the high nibble representing the volume and frequency for the 4 voices:

1000	frequency voice 1	The low	er nibble contains the data
1001	volume voice 1	itself.	Either attenuation from 0 to 15
1010	frequency voice 2	or the	two most significant bits of the
1011	volume voice 2	frequen	cy. Following are the low nibble
1100	frequency voice 3	control	codes for the SOUND voice:
1101	volume voice 3	0100	white noise
1110	noise control	0000	periodic noise
1111	noise volume They ca	n be ORe	ed with the frequency shift:
		0000	high pitch
		0001	medium pitch
		0010	low pitch
		0011	varied by voice 3

EXAMPLES:

SOUND ROUTINES

SOUND OFF

JUMP TA	BLE ADDR	ESS: FD53
ENTRY:	none	
EXIT:	A	255
	С	sound port
		others preserved

DESCRIPTION:

This handy routine turns the volume off on all voices which effectively kills any sound in progress. It should be used whenever an operation (which may have used sound) is aborted. It can also be useful from SmartBasic when a program crashes or ends abruptly leaving the sound blasting. Just CALL 64851 to turn it off.

SOUND ROUTINES

START SOUND

JUMP TA	ABLE ADD	ESS: FD56
ENTRY:	В	sound number to start playing
	HL	pointer to end of sound data
EXIT:	A HL	=0 if successful, non zero value means sound in progress pointer to next note
	IX all ot!	pointer to sound data table er registers used except IY

DESCRIPTION:

This routine gets the relevant vector for the requested sound into IX. It is the programmer's responsibility to save IX for ending the sound. It then checks to see, if a sound is currently in progress and simply returns if so. You must check for A=0 with an OR A instruction since the routine always returns with the zero flag set regardless of success or failure.

The next step is to record the sound number in the internal buffer. After that, the routine decrements the pointer to sound data to extract the address of the NEXT NOTE to play and places it in its PLAY buffer.

Note that no sound is generated by this routine, it just sets up the pointers used by PLAY SOUND on the next page.

SOUND ROUTINES

PLAY SOUND

JUMP TABLE ADDRESS: FD59 ENTRY: none EXIT: Zero flag set means sound is over all registers used except IY

DESCRIPTION:

This routine goes through each of the 4 voice data areas associated with a SOUND. It sends the volume and frequency for each voice. It ends by checking if the SOUND is over and returns with the zero flag set if so. The idea of this routine is to process one set of sound values, return control to the user, and play the next set of values on the next call. Byte 3 is always a frequency value. Byte 4 may be either a voice or a volume commands. Bit 4 of the sound data determines which type of command is sent.

BYTE

0 flag for active voice-channel number or 62(3E) if sound effect. address of sound effect handler if 62 in byte 0 1&2 you may notice that the frequency data is f2 f3 f4 f5 f6 f7 f8 f9 3 not in the correct pattern to send to the sound port. The sound manager takes care 0 0 0 0 0 0 f0 f1 of shifting bits around. 4 .voice ID. see page 80 for details on voice. note length. This value determines if a note is to be repeated (unchanged) several times. Set to 1 to play once. Sweep code. If zero, the note is not to be swept. The lower nibble determines how many SWEEPS to perform and is decremented on each pass. Once it becomes zero, it is reset by using the upper nibble value.

7 Sweep value. If zero, the note is not swept. Other values range from 1 to 127 and -1 to -128. This value is ADDED to the base frequency (bytes 3 and 4) to vary the frequency on the next pass. Sweeps always work on fixed increments.

8 Attenuation (volume) sweep. If zero, then no sweep. It is decremented and reset as byte 6.

9 The top four bits determine the VOLUME change to be applied to the note. A value of 1 increases attenuation by one and a value of 15 decreases attenuation by 1. Any carry (over 16) causes the volume to go from high to low or reverse.

Sound programming is very complex and requires HOURS of analysis and experimentation.... I have not tried. Basically, you set up an NMI interrupt vector to pass control to the SOUND MANAGER on a regular basis. This allows you to go about your business while a sound is being played.

SOUND ROUTINES

END OF SOUND

JUMP TABLE ADDRESS: FD5C ENTRY: DE pointer to sound number HL pointer to next note IX pointer to current sound table EXIT: All registers used except IX and IY

DESCRIPTION:

The input values for HL and IX are the values returned by START SOUND(105). The programmer should have saved these to call END SOUND. The routine saves the pointer to next note in the sound table, gets the sound number and turns off the requested sound.

If all this sounds complicated, it is! Besides, the play sound routines can handle complex instructions like frequency or volume sweeps through a variety of control codes. Several hours of decoding of the associated routines would be required in order to make full use of the sound routines.

Considering all of that, it is no surprise that this EOS area is commonly used by programmers to install special drivers like RAM DISK or HARD DRIVE interfaces.
DECREMENT LOW NIBBLE

JUMP TABLE ADDRESS: FD44 ENTRY: HL pointer to byte to be decremented EXIT: Zero flag set if nibble becomes zero Carry set if result negative

DESCRIPTION:

This routine can be quite useful when working with BINARY CODED DECIMAL numbers. HI. is used as a pointer to the byte containing two digits in question. A call to this routine reduces the least significant digit by one and sets the zero flag if it becomes zero. The carry flag will be set if it becomes negative. The programmer can then affect a borrow on the high nibble to correct the subtract error.

EXAMPLES:

LD	HL,NUMBER	;point to the data.
CALL	FD44	;decrement it.
JR	NC,NOBORROW	;no need to borrow.
CALL	FD47	;make a borrow.
JR	NC, BORROW	;so far so good.

;

;here you need to extend the borrow to the next most significant byte

;

BORROW:

LD	A, (HL)	;get the byte.
AND	ОЕОН	;keep the top nibble.
ADD	A, 9 ;was or	iginally zero so now 9 after borrow.
LD	(HL) ,A ;write	it back.

NOBORROW:

;carry on with routine.

DECREMENT HIGH NIBBLE

JUMP TABLE ADDRESS: FD47

ENTRY: HL pointer to byte EXIT: Zero flag set if nibble becomes zero Carry flag set if result negative

DESCRIPTION:

This routine works like the one on the previous page except that it decrements the upper half of the byte in HL. If a borrow is required, it must be taken from the next most significant byte (if any).

EXAMPLES:

MOVE HIGH NIBBLE TO LOW NIBBLE

JUMP TABLE ADDRESS: FD4A

ENTRY: HL address of byte to move

EXIT: all registers preserved except A

DESCRIPTION:

This routine COPIES the most significant nibble of the byte in HL to the least significant nibble. Other than a precursor to a BCD divide by ten sequence, I can't think of a particularly useful purpose for this routine.

It is used, however, by the sound routines to RESET sweep values. Sweep values range from 0 to 15 and are initially placed in both halves of a byte. The low nibble is decremented until it becomes zero and then reset with the high nibble.

EXAMPLES:

LD HL, COUNTER ;hi-lo nibble as described above CALL FD44 ;decrement low nibble RET NZ ;not ready to take action yet CALL FD4A ;reset the counter in low nibble

;

;here take whatever action is required... one "pass" has been performed.

ADD A AND (HL)

```
JUMP TABLE ADDRESS: FD4D
ENTRY: A signed value to add
HL pointer to 16 bit number
EXIT: A varies
B destroyed
others preserved
```

DESCRIPTION:

This routine adds a signed value in A from +127 to -128 to a 16 bit number pointed to by register HL. The value is stored in the usual LSB, MSB fashion. It adds the value in A to location HL and writes it back. It then adds the carry and sign to the most significant byte.

EXAMPLES:

EOS DATA TABLES

Following is a description of some of the data tables in EOS 6. Most of them are the same in EOS 7.

FC17	to FC26	the numbers 0 to 15 representing the memory configurations.
FC27		port number for bank switching.
FC28		port number for network reset.
FC29		VDP control port.
FC2A		VDP data port.
FC2B		Joystick 0 data port.
FC2C		Joystick 1 data port.
FC2D		Strobe set port (read second half of joystick).
FC2E		Strobe reset port (read first half of joystick).
FC2F		Sound port.
FC30	to FD5F	EOS Jump tablesee next page.
FD60		EOS revision number.
FD61	FD62	Current VDP mode (registers 0 and 1).
FD63		VDP status (on last call).
FD64	FD65	Pointer to Sprite attribute table.
FD66	FD67	Pointer to Sprite pattern table.
FD68	FD68	Pointer to Name table.
FD6A	FD6B	Pointer to Pattern table.
FD6C	FD6D	Pointer to Colour table.
FD6E		Current memory configuration.
FD6F		Last storage device used.
FD70	FD71	Address of current PCB.
FD75		Last keypress register (after call to read keyboard).
FD76	FD85	Printer buffer.
FD86		Media size for INIT.
FD87	FD8A	Current block of storage device.
FDAO	FDB9	Internal search buffer for directory work.
FDBA	FDD3	Internal file control block.
FDD4		Current file number in directory.
FDE0	FE1B	File Manager (see page 96).
FE1C	FE57	Stack.
FE58	FE61	Debounce table for joysticks.
FE62	FE6D	Temporary stack used when switching memory banks.
FE6E	FE78	Sound data tables.
FE79		Character under cursor.
FE7A		Left margin.
FE/B		Right margin.
FE/C		l'op margin.
FE7D		Bottom margin.
FE/E	FE9E	Screen builer (only 33 characters).
FE9F		Number of lines.
FEAU		Number of Columns.
real Feac	F LAZ	nome cursor address.
FEA3	r LA4	Poincer to name table.
reao	FLAO FEC2	Current cursor position.
FECU	FEC3	Processor Control Block (PCB).
EEC4	FFFF	Device Control Blocks (DCB); see page 94

EOS JUMP TABLE

This table lists only some of the jump vectors in the EOS. The ones which serve no purpose and those which are disabled have been omitted. The addresses are written in decimal and HEX. The second column indicates the actual address of the routine in EOS 6.

64560:FC30	JP	F832:63538	initialize EOS	
64563:FC33	JP	F627:63015	console display (no special	characters)
64566:FC36	JP	F5DG:62940	console initialization	
64569:FG39	JP	F60A:62986	display character on screen	(process
specials)				
64572:FC3G	JP	F95F:63839	delay after hard reset	
64575:FC3F	JP	F5B8:62904	end print buffer	
64578:FC42	JP	F57C:62844	end print character	
64581:FC45	JP	FAE2:64226	end read one block	
64584:FC48	JP	FBA5:64421	end read printer	
64587:FC4B	JP	F4E0:62688	end read keyboard	
64590:FC4E	JP	FB13:64283	end write one block	
64593:FC51	JP	FBE1:64481	end write printer buffer	
64596:FC54	JP	F446:62534	find DCB	
64602:FC5A	JP	FA4C:64076	get PCB address	
64605:FC5D	JP	F8F6:63734	hard INIT	
64608:FC60	JP	F94B:63819	hard reset net	
64611:FC63	JP	F515:62741	print buffer	
64614:FC66	JP	F4FC:62716	print character	
64617:FC69	JP	FA9E:64158	read one block	
64620:FC6C	JP	F4BA:62650	read keyboard	
64629:FC75	JP	FA87:64135	read device-return code	
64635:FC7B	JP	FA2F:64047	relocate PCB	
64638:FC7E	JP	F473:62579	request status	
64641:FC81	JP	F4CB:62667	keyboard status	
64644:FC84	JP	F5D2:62930	printer status	
64650:FC8A	JP	F9CB:63947	scan net for devices	
64653:FC8D	JP	F922:63778	soft initialization	
64656:FC90	JP	FA5D:64093	soft reset device	
64659:FC93	JP	FA51:64081	soft reset keyboard	
64662:FC96	JP	FA55:64085	soft reset printer	
64668:FC9C	JP	F580:62848	start print buffer	
64671:FC9F	JP	F56D:62829	start print character	
64674:FCA2	JP	FAC6:64198	start read one block	
64677:FCA5	JP	FB86:64390	start read printer	
64680:FCA8	JP	F4D0:62672	start read keyboard	
64683:FCAB	JP	FAFF:64255	start write 1 block	
64686:FCAE	JP	FBC2:64450	start write printer	
64689:FCB1	JP	F970:63856	synchronize clocks	
64692:FGB4	JP	FAB2:64178	write 1 block	
64695:FCB7	JP	FB75:64373	write printer	

EOS JUMP TABLE

64698:FCBA	JP	EEEA:61162	initialize file manager
64701:FCBD	JP	F323:62243	initialize directory
64704:FCC0	JP	EA00:59904	open file
64707:FCC3	JP	EB04:60164	close file
64710:FCC6	JP	EB6C:60268	reset file
64713:FCC9	JP	E690:59024	make file
64716:FCCC	JP	E61B:58907	find file 1
64719:FCCF	JP	E651:58961	update file in directory
64722:FGD2	JP	EC17:60439	read file
64725:FCD5	JP	ED8F:60815	write file
64728:FCD8	JP	EEC5:61125	put date
64731:FCDB	JP	EED4:61140	get date
64734:FCDE	JP	F10F:61711	rename file
64737:FCE1	JP	F14E:61774	delete file
64740:FCE4	JP	F488:62600	get device status
64743:FCE7	JP	FA94:64148	exit to WP
64749:FCED	JP	F241: 62017	trim file
64752:FCF0	JP	F089:61577	find file in FCB
64755:FCF3	JP	F17B:61819	read block
64758:FCF6	JP	F1E6:61926	write block
64761:FCF9	JP	FOD9:61657	mode check
64764:FCFC	JP	EF0B:61195	look up file in directory
64767:FCFF	JP	E618:58904	find file 2
64785:FDll	JP	E191:57745	set VDP port data
64788:FD14	JP	E185:57733	switch memory banks
64791:FD17	JP	E153:57683	put ASC in VDP
64794:FD1A	JP	E000:57344	write VRAM
64797:FDlD	JP	E01A:57370	read VRAM
64800:FD20	JP	E034:57396	write VDP register
64803:FD23	JP	EO4F:57423	read VDP register
64806:FD26	JP	E059:57433	fill VRAM
64809:FD29	JP	E066:57446	initialize VRAM tables
64812:FD2C	JP	E0C9:57545	put VRAM
64815:FD2F	JP	E0CF:57551	get VRAM
64818:FD32	JP	E10A:57610	calculate pattern position
64821:FD35	JP	E129:57641	point to pattern position
64824:FD38	JP	E149:57673	load default ASCII to VDP
64827:FD3B	JP	E1C5:57797	write sprite table
64830:FD3E	JP	E253:57939	read game controller
64833:FD41	JP	E2A4:58020	update spinner
64836:FD44	JP	E355:58197	decrement low nibble
64839:FD47	JP	E35F:58207	decrement high nibble
64842:FD4A	JP	E369:58217	move high nibble to low nibble
64845:FD4D	JP	E374:58228	add A + (HL)
64848:FD50	JP	E3AB:58283	sound initialization
64851:FD53	JP	E3D1:58321	sound off
64854:FD56	JP	E3E7:58343	start sound
64857:FD59	JP	E406:58374	play sound
64860:FD5C	JP	E4B8:58552	end of sound

ERROR CODES

The EOS returns a variety of error codes. Several of these are errors returned by the Device Control Blocks. In order to interpret these from the table below, the high bit must be stripped with an AND 7F.

	1	DCB not found
	2	DCB busy
	3	DCB idle
	4	No date
	5	No file
	6	File exists or printer busy
	7	No available FCB
	8	Match error, file incompatible
	9	bad file number (greater than 2).
10	End of file (re	eading past end of file).
11	File too big	
12	Directory full	or no key pressed on keyboard read
13	Storage media f	full
14	File number er	cor
15	Rename error	
16	Delete error	
17	Range error or	bad mode
18	Synchronize er	cor on clock
19	Synchronize er	cor byte 2
20	Mode incompatik	ole with access request; e.g. reading a read protect
file		
21	Media status en	ror
22	Device error, u	usually with tapes or disks
23	Program non exi	stent
24	Storage medium	fails directory validity check
27	Device time out	

MEMORY BANKS

The ADAM can access 64K of memory at a given time. This memory, however can be switched in different combination of upper and lower 32K segments. These provisions allow the switching in of a GAME CARTRIDGE, the EOS ROM, Expansion memory₁ etc. Following are the memory configuration codes to send to the BANK

SWITCH ROUTINE(15):

CODE	LOWER 32K	UPPER 32K
0	SmartWriter ROM	Normal RAM
1	Normal RAM	Normal RAM
2	Expansion RAM	Normal RAM
3	Os 7	Normal RAM
4	SmartWriter ROM	Expansion ROM
5	Normal RAM	Expansion ROM
6	Expansion RAM	Expansion ROM
7	OS 7	Expansion ROM
8	SmartWriter ROM	Expansion RAM
9	Normal RAM	Expansion RAM
10	Expansion RAM	Expansion RAM
11	OS 7	Expansion RAM
12	SmartWriter ROM	Cartridge ROM
13	Normal RAM	Cartridge ROM
14	Expansion RAM	Cartridge ROM
15	Os 7	Cartridge ROM

The default set up for cartridge games is 15: use the OS 7 in lower memory and the cartridge in upper.

NORMAL RAM setting is used by SmartBasic and several other software. Generally, software which uses the blue and yellow SmartKey displays use OS 7 in lower memory and normal RAM in upper (3).

Expansion ROM was intended to be used for some ROM based software which could instantly be booted like SmartWriter when you power up the system.

SmartWriter uses configuration 0.

DEVICE CONTROL BLOCK STRUCTURE

The ADAM has more than one processor controlling its operations. The USER uses the Z-80 processor, and the network is controlled by several 6801 processors. The main 6801 accesses device control blocks in the EOS to and receive data according to the commands placed in the device control blocks. Each DCB is 21 bytes organized in the following fashion:

send

0	Command and/or status byte
1-2	Address where to put or get data
3-4	Size of device buffer (Keyboard-1, Printer-16)
5-8	Block number requested (for tapes and disks)
9	Secondary device (see below)
10-13	Unused
14-15	Retry count, how often before quitting
16	Device number
17-18	Maximum length of device buffer
19	Device type (O-character, 1-block)
20	Device dependent status flag (the one that detects missing
media)	

Device commands are placed in DCB+0 and the device acknowledges by placing a value 80HEX or greater in DCB+0. If the value is greater than 80HEX, there is an error. There are only 5 commands:

0	Idle, effectively disables the device
1	Request status
2	Reset device
3	Write
4	Read

The EOS has room for 15 devices. Following is a list of what COLECO had expected to supply as devices:

1	Keyboard	8	Tape 1
2	Printer		9 Tape 3
3	Copywriter	10	?
4	Disk 1	11	Modem (not the Adam Link)
5	Disk 2	12	High Resolution Monitor
6	Disk 3	13	Centronics Interface
7	Disk 4	14	RS-232 Interface
		15	Gateway

Note that tape 2 is not listed. That is because tapes 1 and 2 share the same DCB. When requesting an operation on tape 2, the request is sent to the DCB for tape 1 with the number 18HEX in the secondary device ID in byte 9. The device status flag (20) is split in two nibbles. The upper represents the alternate device while the lower represents the main device. This status bit is similarly coded for the disk drives as well.

FILE CONTROL BLOCK STRUCTURE

The EOS has three file control blocks. The first is used exclusively for directory searches and cannot be utilized for a user file. The other two are used by the EOS in response to an OPEN FILE(38) request. Thus you can have two files opened at once (e.g. read form one and write to the other) provided they are on the same medium. A file control block has 36~bytes and is organized as follows:

```
0-11 File name
12 File attributes
13-16 Start block of file
17-18 Blocks allocated to the file
19-20 Blocks actually used
21-22 Bytes used in the last block
```

-----same as a directory entry

```
23
       Device number corresponding to the file
24
       File mode 0-unused (available)
       1-read
       2-write
       3-update
       4-fill rest of space on medium
25-28
              Current block being used
29-32
              Last block of file (or volume size if Directory FCB)
               Byte position in current block
33-34
35
               Length of FCB
```

While it may be interesting to know what the structure of an FCB is, the programmer normally does not need to worry about the details. The EOS file operation functions can take care of all the housekeeping related to a file.

FILE MANAGER STRUCTURE

The File Manager is an internal data storage area used by the EOS to process file commands. The various routines put and get information there when working with files. The File manager is 60 bytes long:

0	System Year
1	System Month
2	System Day
	entry
3-14	File name
15	Attributes
16-19	Start Block
20-21	Blocks allocated to file
22-23	Blocks actually used
24-25	Bytes used in the last block
26	File Year
27	File Month
28	File Day
	same as directory entry
29-30	Pointer to File Control Block
31-32	Pointer to Directory buffer
33	File number
34-35	Bytes requested (read or write)
36-37	Bytes not processed, yet
38-39	User's buffer to send/receive data
40-41	Pointer to FCB buffer
42-43	Pointer to end of FCB buffer
44-47	Block number currently working on
48-49	Pointer to user's file name
50-53	Block number or volume size
54-57	Block number for start of BLOCKS LEF'T (after adding current file
size)	
58-59	Size of BLOCKS LEFT; space remaining on medium

As with the file control blocks, the EOS routines take care of manipulating all the information described above.

;This program illustrates several of the EOS functions described in this manual. It has been deliberately abbreviated and certain cosmetic improvements suppressed in order to keep it short. You will note that the bulk of the program is data in the form of messages. Although the entire package may appear lengthy, adding more functions will add very little to the existing code since most of the groundwork has already been laid. This is the advantage of creating modular routines which can be shared.

;

;The program has 5 functions accessed by pressing Smart Keys

; ;	I with ba	string input from the keyboard ckspace editing
;		
; ;	II	ordinary string printing using extra line feeds for spacing
;		
; ;	III and tur	How to move the cursor around n on inverse video
;		
;	IV	writes data to a file
;		
;	V	reads data from a file

;

;It is worthwhile to study the entire code as there are quite a few programming tricks included within the code itself. At the end of the code ;listing, you will find full HEX listing in order to POKE the data in. To make a self booting disk, a simple method is to copy blocks zero and one ;of your SmartBasic medium to a new medium. Then delete all the files form the directory EXCEPT the BASICPGM file. The next step is to ;write all the data starting at block 2 of the media. This can be easily done with CLONE.COM in TDOS. DO NOT change the file size in the ;directory unless you change the corresponding parameter in the boot block.

;

; If you would like a CP/M disk copy of the source code along with a BOOTABLE version of the DEMO, please send \$5.00 to the author. All ;profits will be channeled back into ANN to fund other projects.

;

;Let's start by defining a few equates for the assembler

;* JUMP TABLE VECTORS *

F'CBDEVICE	EQU	0FD6FH	;where EOS stores the default
drive			
CONDISP	EQU	0FC33H	;print characters without
controls			
INITCON	EQU	0FC36H	;set up the window
CONOUT	EQU	0FC39H	;print character with control~
END_RD_KYB	EQU	0FC4BH	
START_RD_KYB	EQU	0FCA8H	
OPENF	EQU	OFCCOH	;open file
CLOSEF	EQU	0FCC3H	
QUERYF	EQU	OFCCCH	;find exact file name (including type)
ISFILE	EQU	OFCFFH	;does file name exist
MAKEF	EQU	0FCC9H	
READF	EQU	0FCD2H	
WRITEF	EQU	0FCD5H	
GO_WP	EQU	0FCE7H	;exit to SmartWriter
WR'IVREG	EQU	0FD20H	
FILLVRAM	EQU	0FD26H	
INITTBL	EQU	0FD29H	;set up VDP table
LOADASCIT	EOU	0FC38H	:get ASCII in default location
PUTASCII	EOU	0FC17H	; put ASCII in specified place
101110011	770	0101/11	, pat moori in specifica piace

;

;

;********	*******************************						
;*			KEYBOARD KEYS *				
;********** ;	****	****	*****				
CTLC LEFT SK1 SK2 SK3 SK4 SK5 SK6	EQU EQU EQU	03H 0A3H 81H EQU EQU EQU EQU	;abort key CONTROL-C ;keft arrow ;smart keys 82H 83H 84H 85H 86H				
;	****	****	****				
;*	OTHER E	QUATES	*				
;********	******	****	****				
;							
ESC EOS BS LF CR CLRSCR	EQU EQU EQU EQU EQU	1BH 0H 8H 0AH 0DH 0CH	escape end-of-string ;back space ;line feed ;carriage return ;clear screen				
;	;						
·*************************************	******	****	*****				
;*	LET'S G	ET GOING	5*				
·*********	***********						

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LD	HL,45EDH	;a RETURN NMI	
LD	(66H),HL	;disable NMI ASAP	
LD	SP, STACK	;set up local stack	
LD	A, (FCBDEVICE)	;get the boot device	
LD	(DRIVE),A	;save boot drive	

;SET UP SCREEN

CALL	SETBORDO ;	set border colour
CALL	WRTVREG	to register o
LD	BC,01COH ;	send CO to register 1
CALL	WRTVREG ; set up V	VDP mode
LD	HL, O	
LD	A, 2 ;pattern	name
CALL	INITTBL ; set the	table
LD	нь,0340н	
LD	A,4 ;pattern	colour
CALL	INTLER	
ם ד ח	A 3 · nattern	generator
CALL	INITTRI.	generator
LD	HL,3800H	
LD	A,1 ;sprite p	oattern
CALL	INITTBL ; though i	unused here, we must
LD	HL,3880H ;	make sure they do not conflict
XOR	A ;=0 sprit	te attributes
CALL	INITTBL	
CALL	SETNORM ; set cold	ours
CALL	SETINV	
ТD	A, ' ' ; use space	ces fill whole career
ם ב ת	HIO at the r	nattern table
CALL	FILLVRAM	
CALL	LOADASCII ;	gimme some characters
LD	HL,0	
LD	BC, 80H	
LD	DE,OCOH	
CALL	PUTASCII ;	and some inverse
LD	BC,1E17H ;	30 columns, 23 rows
LD	HL, 0000 ;	pattern name table
LD	DE,100H;home pos	sition

CALL	INITCON ; set it	up				
CALL	START_RD_KYB	;so we	can use	END READ	to	get

;

- .
- ;

;* MAIN MENU

]	MAIN:	CALL LD LD CALL	CLS ;clear DE,0 ;send ~ HL,MAINMENU PRTLOC :print	off a ;print this message
]	MAINO:	CALL CP JP	CIN ;get a CTLC ;is it Z,QUIT	character, wait for it abort?
		LD	DE,MAIN;set to	return to main
		PUSH	DE ;after	each function
		CP	SKl	
		JP	Z,KEYIN ;demo k	eyboard
		CP	SK2	
		JP	Z,PRTMSG	;demo printing
		CP	SK3	
		JP	Z,GOTOXY	;let's move around
		CP	SK4	
		JP	Z,MAKEFILE	;make a file
		CP	SK5	
		JP	Z,READFILE	;let's peek at one
		CP	SK6	

JP Z,QUIT ; ;get here if no matching menu was pressed ; POP DE ;level off stack JR MAINO ;try again

;

;* FUNCTION I * ;* Demo of keyboard input *

;

KEYIN:

LD	HL, TYPEMSG	,give user a prompt
CALL	PRTSTR ;print :	it
LD	B,30 ;read no	o more than 30
LD	HL, BUFFER	;into this buffer
CALL	C INBUFF	;use our editor
LD	HL, BUFFER	;start at beginning

CASE:

LD	A, (HL)	;get a character
OR	A	;is it zero?
JR	Z,CDONE	if end of string then we are done
CALL	UPCASE	;convert to uppercase if letter
LD	(HL) ,A	;replace character even if same
INC	HL	;advance pointer
JR	CASE	;loop until we are done

CDONE:

LD	HL,YOUSAID	;let user know we are echoing
CALL	PRTSTR	
LD	HL,BUFFER	;point to buffer

CALL	PRTSTR	;print it
CALL	CRLF	;next line
CALL	HITKEY	;print ANY KEY message and get key
RET		;done this function

*

*

;* FUNCTION II ;* Printing to Screen

;

;

PRTMSG:

LD	HL,HEREMSG ;print at current position
CALL	PRTSTR
CALL	HITKEY ;wait for user to be ready
LD	HL, SCROLL ;this is a message which forces scroll
CALL	PRTSTR
CALL	HITKEY
LD	HL,SKIPLINE ;this message skips a few lines
CALL	PRTSTR
CALL	HITKEY
LD	HL, LONG ;this long messages wraps around
CALL	PRTSTR
CALL	HITKEY
RET	

;

;*	FUNCTION III	*
;*	Moving the cursor	*

;

GOTOXY:

LD HL, WATCHIT ;print this message LD DE,1005H row 16 column 10 CALL PRTLOC ;routine places cursor and prints LD B,30 ;we¹ll move 30 times LD HL,MOVET ;using the table below

MOVEC:

```
LD A, (HL);get one
CALL COUT ;send it
LD DE,33333 ;wait for this long
```

WAIT:

DEC	DE
LD	А, Е
OR	D ;is DE=0?
JR	NZ,WAIT;let's wait some more
INC	HL ;advance pointer
DJNZ	MOVEC ;repeat until B=0
LD	A, 24 ;clear to end of screen
CALL	COUT ;print the character
LD	BC,65535
CPIR	;another non destructive way to wait
CALL	IVON ;set to print high bit
LD	HL, IVMSG ;print this message
CALL	PRTSTR ;will use alternate colour
CALL	IVOFF ;back to normal video
CALL	HITKEY
	RET

MOVET:

DB	160,160,160,163,163,163,160,163,160,163
DB	160,160,160,163,163,163,160,163,160,161
DB	160,163,160,161,160,163,160,161,160,163

;

;*	FUNTION IV	*
;*	Writing to file	*

;

MAKEFILE:

LD	HL, GETFNAME
CALL	PRTSTR ;ask user for a file name
LD	HL, BUFFER ;put it here
LD	B,11 ;max 11 characters
CALL	CINBUFF;do it
LD	HL, BUFFER ;reset to start
XOR	A ;look for null

LD	BC , 11	;we know	w there is a null
CPIR		;within	11 bytes for a name
LD	(HL) ,	3	;mark end of file name
DEC	HL		
LD	(HL) ,	'A'	;file type

LD	A, (DRIVE) ;look on default device
LD	DE,BUFFER ;match this name
LD	HL, DIRENTRY ; save here if found
CALL	ISFILE ;match type A or H of file
JR	NZ,NOFILE ;good, we're not killing anything
LD	HL, EXISTS ;tell user
CALL	PRTSTR ;the file is there
JR	MAKEFILE ; and try again

NOFILE:

;

LD	DE,HEREN	4SG	;start	here	
LD	HL,WATCH	TIH	;end he	ere	
OR A		;clear d	carry		
SBC	HL,DE	;HL=size	e of fi	le	
LD	В,Н				
LD	C,L	; copy to	D BC		
	·	. 11			
T.D	HL. FIL	RUFF	:file s	start	
	,	10011	,	Cur c	

MOVEDATA:

LD	A, (DE)	;get a byte
CP	LF	
JR	Z,IGNORE	;remove all formatting
СР	CR	
JR	Z, PUTSPC	;put space for <cr> for wrap</cr>

СР	EOS
JR	NZ, PUTCHR ; if not END then put the character
LD	A, CR ;now put a <cr></cr>
JR	PUTCHR

PUTSPC:

LD A,''; a space

PUTCHR:

LD	(HL) ,A;put in buffer
INC	HL ;increment buffer

IGNORE:

INC	DE	;increment raw source
DEC	BC	;decrement byte count
LD	A,B	
OR C		;is BC=0?
JR	NZ ,MOV	EDATA ;not done yet
LD	DE, FIL	EBUFF ;this is the start
XOR	A	;clear carry
SBC	HL,DE	;this is the modified file size
LD	BC , 0	
LD	D,H	
LD	E,L	;BCDE=size

PUSH DE ;save file size LD A, (DRIVE) ; get the default drive HL, BUFFER ; point to file name LD CALL MAKEF ; make the file JR NZ, ERROR ;oops LD A, (DRIVE) ; get drive back B,2 ;WRITE mode LD CALL OPENF ; HL is still pointing to name NZ, ERROR JR LD (FNUM) ,A ;save file number for close BC ; get back file size POP HL, FILEBUFF ;start writing here LD CALL WRITEF ; do it in one pass NZ, ERROR JR LD A, (FNUM) ; get file number back again CALL CLOSEF ; close it off NZ,ERROR JR LD HL, DONEMSG ;tell user CALL PRTSTR ; we are done CALL HITKEY RET

ERROR:

LD HL, ERRORMSG ;we're not interpreting errors here CALL PRTSTR ;just tell user CALL HITKEY ; and get out

RET

*

;* FUNCTION V ;* Reading from a file

;

;

READFILE:

LD	HL, GETFNAME ;ask user
CALL	PRTSTR ; for file name
LD	HL BUFFER ;put it here
LD	B,11 ;maximum length
CALL	CINBUFF; use our editor
LD	HL, BUFFER ;point to start
XOR	A ;look for null
LD	BC,11 ;we know there is a null
CPIR	;within 11 bytes for a name
LD	(HL) , 3 ;mark end of file name
DEC	HL
LD	(HL), 'A' ;file type
LD	A, (DRIVE) ;look on default device
LD	DE, BUFFER ;match this name
LD	HL, DIRENTRY ;save here if found
CALL	QUERYF ;exact match this time
JR	Z, GOTFILE
LD	HL, BADNAME ;tell user
CALL	PRTSTR ;there is no file
JR	READFILE ; and try again

GOTFILE:

LD	A, (DRIVE) device
LD	B,1 ;read mode
LD	HL, BUFFER ;file name
CALL	OPENF ;try and open
JR	NZ, ERROR ; oops
LD	(FNUM) A ;save number for close
LD	BC,5006 ;maximum we want to read
LD	HL, FILEBUFF ;start of buffer
CALL	READF ;bring in 5000 or less bytes
JR	Z NOERROR ;file was at least 5000
CP	i6 ; is it end of file?
JR	NZ,ERROR ;oops

;here you should flag that all file is not read yet

;

NOERROR:

LD A, (FNUM) ;get back file number CALL CLOSEF ;we'll close it now though normally we JR NZ,ERROR ;would wait till completed.

;

;now we'll print the file with a word wrap.

;

CALL	CRLF ;ad	vance to new	w line
LD	DE, FILEBUE	'F ;start	of buffer

ECHOMORE:

XOR	A	;load A with 0	
LD	(DIDWRA	P) ,A ;reset the NEWLINE	flag
LD	HL, 30	;screen width	
ADD	HL,DE	;this is MAX end of line	

FINDWRAP:

LD	A, (HL)
CP	' ' ;is this character a space
JR	Z,GOTWRAP ;good, let's wrap here
CP	CR ;is it already a NEW LINE
JR	Z,DOLINE ;a <cr> forces wrap anyway</cr>
DEC	HL ;back up one character and try again
JR	FINDWRAP ;will crash if no space in30 characters

GOTWRAP:

LD	(HL) , 255	;mark with unique character

DOLINE:

LD	A,(DE)	;get	: cł	narad	cter	from	original	position
CP	255	;is	it	the	NEW	LINE		
JR	Z,DOWRA	P		;le	et's	do it		

CP	CR ;or i	already newline?
JR	NZ,SKIPWRAP	;nope then don't wrap

;

;

,

;

DOWRAP:

LD	(DIDWRAP) ,A	;set the WE DID A WRAP
CP	255	;if (DE) was 255 then reset it
JR	NZ, CHECKHL	;nope, then check if (HL) was set
LD		
LD	(DE) ,A	

CHECKHL:

LD	A, (HL)	;always check (HL) regardless of (DE)
CP	255	;had we put a force there?
JR	NZ , DOW1	
LD	(HL),''	;replace the stolen space

DOW1:

LD CALL	A, CR COUT	;now let's put a <cr></cr>
LD	A,LF	;followed by a <lf></lf>

SKIPWPAP:

CALL	COU	Г									
PUSH	HL	;save	HL								
LD	HL,	1000	;wait	а	bit	just	for	the	heck	of	it

SLOW:

DEC	HL
LD	А,Н
OR	L ;is HL zero?
JR	NZ,SLOW ;wait some more
POP	HL ;restore HL
INC	DE ;advance pointer
DEC	BC ;one less byte in file
LD	А,В
OR	C ;is file done?
JR	Z, FILEDONE ;then let's get out
LD	A, (DIDWRAP) ;did we wrap.
OR	A ;will be non-zero

JR	Z,DOLINE	;let's	work on	this line	some more
JR	NZ, ECHOMORE	;let's	start a	new line	

FILEDONE:

CALL CRLF ;Skip line for clarity CALL HITKEY RET

;

;* EXIT ROUTINE

;

QUIT:

LD	SP,OFFFFH	;set stack in safe place
JP	GO_WP ;get	outa here

;

;* CHARACTER I/O

;

CRLF: LD HL,CRLFMSG ;point to a <CR><LF> JR PRTSTR ;print it

;

GOTORC:

PUSHDE; save requested positionLDA,D; reverse DELDD,E; cause I like to goto XYLDE,A; rather than GOTO YX

INC	D	
LD	A, 1CH	;goto xy prefix
CALL		COUT ;print the darn thing
POP	DE	;restore original request
RET		

PRTLOC:

|--|

PRTSTR:

LD	A, (HL)	;get a byte
CP	EOS	;is it END
RET	Z	;get outa here
CALL	COUT	;print one character
INC	HL	;advance pointer
JR	PRTSTR	;keep going til end

IVON:

	LD	A,	80H	;set	to	add	128	in	COUT	routine
IV0:	LD	(I	NVERS	E) ,A						
	DET									

UPCASE:

CP	'a'	;is it less than a
RET	С	;don't convert
CP	'z'+1	;is it bigger than z
RET	NC	;don't convert
AND	5FH	strip the LOWERCASE bit
RET		

CLS:

LD	A,CLRSCR	;this	is	the	clear	screen	code	
JP	COUT ;pri	nt it						

;

;reads B characters into (HL)

;space pads to end of buffer after <CR>

;

CINBUFF:

LD	С,О	;set	counter
----	-----	------	---------

CIBUF1:

CALL	CIN ;get a character
CP	CR ; is it ENTER?
JR	Z,CIBUF2 ;flush buffer if so
CP	BS ;was it BACKSPACE
JR	Z,DESTBS ;do it
CP	LEFT ;left arrow as well

JR	Z,DESTBS
CP	ESC ;cancel request
RET	Z ;get out NOW
GP	CTLC ;was it abort
JP	Z,MAIN ; go back to MAIN
CALL	COUT ;echo the character
LD	(HL) ,A ;put it in buffer
INC	C ;one more character in
INC	HL ;advance buffer pointer
DJNZ	CIBUF1 ;decrement MAX count & continue if safe
CP	BS ;was last character a BACKSPACE
JR	Z,DESTBS ;do it again
CP	LEFT
JR	Z,DESTBS
CP	ESC ;was last a cancel
RET	Z
CP	CTLC ;was last an abort
JP	Z ,MAIN

CIBUF2:

LD	(HL) ,0	;mark end of string
LD	Α,Β	
OR	А	
RET	Z ;we rea	ad in the maximum requested

CIBUF3:

INC	HL ;ski	p to next character
LD	(HL),''	;space fill it
DJNZ	CIBUF3 ;up	to requested length
RET		

DESTBS:

LD	A,C ;what is the position
OR	A
JR	Z,CIBUF1 ;can't <bs> if at start</bs>
LD	A,BS ;print a backspace
CALL	COUT
LD	A ,' ' ;write a space over old character
CALL	COUT
LD	A, BS ;backspace into hole
CALL	COUT
DEC	HL ;reduce pointer
DEC	C ;and the character count
INC	B ;make one more available
JR	CIBUF1 ;and try again
SAMPLE PROGRAM

HITKEY:

LD	HL,ANYK	EYMSG	;a	sk u	ser t	to	press	key
CALL	PRTSTR	;print	it	and	fall	tl	hrough	

CIN:

PUSH	BC	;save all registers
PUSH	DE	;except A
PUSH	HL	

CIN1:

RET		CALL JR PUSH CALL POP POP POP POP RET	END_RD_KYB NC ,CIN1 AF ;save START_RD_KYB AF ;rest HL ;and DE BC	;is there a character ;wait character ;restart the read ore character all registers
-----	--	---	---	--

COUT:

PUSH	AF ;save all registers
PUSH	BC ; including the character to print
PUSH	DE
PUSH	HL
OR	A ; is the character HIGH BIT
JP	M,COUTO ; if high bit set then control
CP	' ' ;is it less than 32
JR	NC , COUT1 ; if >than space then print normal

COUT0:

CAL	L C	TUONC	;this	one	displays	specials	COUT2
JR	C	OUT2					

COUT1:

	OR	0			
INVERSE			EQU	\$-1	;add inverse if it is on
	CALL	CONDISP	;this	one does	not display specials

COUT2:

CALL JR	END_RD_KYB NC ,COUT3	<pre>;check for key waiting ;none so let's get out</pre>
CALL	CIN ;get th	ne character
CP	'S' -40H	;is it CONTROL-S
JR	NZ,COUT3	;ignore if not
CALL	CIN ;wait f	for another character
CP	'C' -40H	;but abort if CONTROL-c
JP	Z,MAIN	

COUT3:

POP	HL	;restore all registers
POP	DE	
POP	BC	
POP	AF	
RET		

;

;* SUBROUTINES

;

;set the border colour

;

SETBORD0:

LD A, (BORDCOL) ;get the default border colour LD C,A ;into register C LD B,07H ;write to VDP register 7 JP WRTVREG;do it and return

SAMPLE PROGRAM

;set the normal and inverse colours

SETNORM:

A, (NCCOL) ; this is the set colour LD А SLA SLA А SLA А SLA A ;normal set colour *16 LD D,A A, (NBCOL) ;clear colour LD OR D LD DE,10H ;write 16 bytes HL, 0340H ;starting here LD ;for character 0-127 JP FILLVRAM

;set inverse colour, differently from above

SETINV:

LD	A, (IBCOL)	;clear colour
LD	D,A	
LD	A, (ICCOL)	;set colour
SLA	A	
OR	D	
LD	DE,10H ;16 byt	es
LD	н∟, 0350н	;start here
JP	FILLVRAM	;for 128-255

;* MESSAGES

DB

ANYKEYMSG:

'Press any key to continue...',EOS

MAINMENU:

DB	'Ι	Keyboard input' ,CR,LF
DB	'II	Print Message' ,CR,LF
DB	'III	Cursor Movement' ,CR,LF

DB	'IV	Make File',CR,LF
DB	. A	Read File' ,CR,LF
DB	'VI	Exit', CR, LF, LF, LF, LF, EOS

;

;used by function I

;

TYPEMSG:

DB 'Type in something' ,CR,LF,LF,EOS

YOUSAID:

DB CR, LF, 5fh, 5fh, 5fh, 'This is what you said: ', CR, LF, EOS

;

;used by function II

;

HEREMSG:

DB	'Normally, messages are printed'
DB	CR,LF,'at the current cursor position.'
DB	CR,'It is up to you to remember'; (last line forced wrap)
DB	CR,LF, 'where you last left the cursor.'
DB	CR,'If the last character of a line'
DB	CR,'is on the margin a scroll is'
DB	CR,LF, 'performed. Be careful when'
DB	CR,LF,' formatting your data.',CR,LF,LF,EOS

SKIPLINE:

DB	CR,LF,LF, 'This message skips lines'
DB	CR,LF,LF, 'To appear double spaced'
DB	CR,LF,LF,'You only need an extra <lf>',CR,LF,LF,EOS</lf>

SCROLL:

DB	CR,LF,LF, 'This -message is near the bottom'
DB	CR, 'of the screen. It will scroll'
DB	CR,LF, 'smoothly when I reach the end'
DB	CR,LF, 'of the screen. The scroll is'

CR,LF, 'handled by the EOS.',CR,LF,LF,EOS

LONG:

DB

DB	CR,LF, 'This message is very long and has not been '
DB	'formatted for the screen. Although all the characters '
DB	'are there, it is difficult to read because words are '
DB	'truncated. See the file read function for more.', CR, LF, EOS

SAMPLE PROGRAM

;

;used by function III

;

WATCHIT:

	DB DB	'Column 5 row 16',CR,LF 'Watch the cursor move around' ,EOS
IVMSG:		
DB DB DB DB DB DB	CR, LF, ' CR, LF, ' CR, LF, ' CR, LF, ' CR, LF, ' CR, LF, '	This message is printed In inverse video. It is accomplished by setting the color table for the high bit characters to make them another color ',CR,LF,LF,EOS
;		
;used by function IV		
;		
ERRORMSG:		
	DB	CR,LF,LF, 'I/O error' ,EOS
DONEMSG:		
	DB	CR,LF,LF, 'Operation Complete' ,CR,LF,EOS
EXISTS:		
	DB	CR,LF,LF, 'File Exists, use another name' ,EOS
GETFNAME:		
	DB	CR,LF,LF, 'Input File Name: ',EOS

;

;used by function V

;

BADNAME:

		DB	CR,LF,'	File Not	Found,	try a	again',EC	S	
;									
;*********	******	****							
:*	DATA &	STORAGE			*				
•************* '	*****	*****							
;									
CRLFMSG:									
		DB	CR,LF,E	OS					
BORDGOL:									
		DB	07Н	;border	colour	saved	here		
NCCOL:									
		DB	OlH	;charact	er SET	colou	r		
NBCOL:									
		DB	OFH	;charact	er CLEA	R col	our		
ICCOL:									
		DB	OlH	;inverse	e SET co	lour			
IBCOL:									
		DB	07H	;inverse	e CLEAR	colou	r		

DRIVE:

		DS	1	;default drive
FNUM:				
		DS	1	file number for READ/WRITE
DIDWRAP:				
		DS	1	;word wrap flag for file print
;				
DIRENTRY:				
	DS	26		;store directory entry here
BUFFER:				
	DS DS	100 100		;room for keyboard input ;stack space
STACK:				
FILEBUF	F: END			;use this area for file I/O

SAMPLE PROGRAM HEX CODE FIRST BLOCK

21 ED 45 22 66 00 31 82 OA 3A 6F FD 32 9D 09 CD 87 04 01 00 00 CD 20 FD 01 C0 01 CD 20 FD 21 00 80 3E 02 CD 29 FD 21 40 03 3E 04 GD 29 FD 21 00 08 3E 03 CD 29 FD 21 00 38 3E 01 CD 29 FD 21 80 38 AF CD 29 FD CD 90 04 CD A9 04 3E 20 11 00 03 21 00 00 CD 26 FD CD 38 FD 21 00 00 01 80 00 11 00 0C CD 17 FD 01 17 1E 21 00 00 11 00 01 CD 36 FC CD A8 FC CD E8 03 11 00 00 21 DF 04 CD C9 03 CD 47 04 FE 03 CA B2 03 11 74 01 D5 FE 81 CA AD 01 FE 82 CA DC 01 FE 03 CA 01 02 FE 84 CA 56 02 FE 85 CA FA 02 FE 86 CA B2 03 D1 48 D3 21 53 05 CD CC 03 06 1E 21 BA 09 CD ED 03 21 BA 09 7E B7 28 07 CD DF 03 77 23 18 F5 21 68 05 GD CC 03 21 BA 09 CD CC 03 CD B8 03 CD 41 04 C9 21 86 05 CD CC 03 CD 41 04 21 CE 06 CD CC 03 CD 41 04 21 77 06 CD CC 03 CD 41 04 21 66 07 CD CC 03 CD 41 04 G9 21 32 08 11 05 10 GD G9 03 06 1E 21 38 02 7E CD 58 04 11 35 82 1B 7B B2 20 FB 23 10 F1 3E 18 CD 58 04 01 FF FF ED B1 CD D9 03 21 60 08 CD CC 03 CD D6 03 GD 41 04 G9 A0 A0 A0 A3 A3 A3 A0 A3 A0 A3 A0 A0 A0 A3 A3 A3 A0 A3 A0 A1 A0 A3 A0 A1 A0 A3 A0 A1 A0 A3 21 64 09 CD CC 03 21 BA 09 06 OB CD ED 03 21 BA 09 AF 01 OB 00 ED B1 36 03 2B 36 41 3A 9D 09 11 BA 09 21 AO 09 CD FF FC 20 08 21 43 09 CD CC 03 18 CE 11 86 05 21 32 08 B7 ED 52 44 4D 21 82 0A 1A FE 0A 28 10 FE 0D 28 08 FE 00 20 06 3E 0D 18 02 3E 20 77 23 13 0B 78 B1 20 E5 11 82 0A AF ED 52 01 00 00 54 5D D5 3A 9D 09 21 BA 09 CD C9 FC 20 28 3A 9D 09 06 02 CD C0 FG 20 1E 32 9E 09 C1 21 82 OA CD D5 FC 20 12 3A 9E 09 CD G3 FC 20 0A 21 2B 09 CD CC 03 CD 41 04 C9 21 1E 09 CD CC 03 CD 41 04 C9 21 64 09 CD CC 03 21 BA 09 06 0B CD ED 03 21 BA 09 AF 01 OB 00 ED B1 36 03 2B 36 41 3A 9D 09 11 BA 09

21 A0 09 CD CC FC 28 08 21 79 09 CD CC 03 18 CE 3A 9D 09 06 01 21 BA 09 CD C0 FC 20 B7 32 9E 09 01 88 13 21 82 0A CD D2 FG 28 04 FE 0A 20 A5 3A 9E 09 CD C3 FC 20 9D CD B8 03 11 82 0A AF 32 9F 09 21 1E 00 19 7E FE 20 28 07 FE 0D 28 05 2B 18 F4 36 FF 1A FE FF 28 04 FE 0D 20 18 32 9F 09 FE FF 20 03 3E 20 12 7E FE FF 20 02 36 20 3E 0D CD 58 04 3E 0A CD 58 04 ES 21 E8 03 2B 7G B5 20 FB E1 13 0B 78 B1 28 08 3A 9F 09 B7 28 C6 20 AE CD B8 03 CD 41 04 C9 31 FF FF C3 E7 FC 21 95 09 18 0F D5 7A 53 5F 14 3E IC CD 58 04 D1 C9 CD BD 03 7E FE 00 C8 CD 58 04 23 18 F6 AF 18 02 3E 80 32 6A 04 C9 FE 61 D8 FE 7B D0 E6 5F C9 3E 0C C3 58 04 0E 00 CD 47 04 FE 0D 28 28 FE 08 28 2F FE A3 28 2B FE 1B C8 FE 03 CA 74 01 CD 58 04 77 0C 23 10 E1 FE 08 28 17 FE A3 28 13 FE 1B C8 FE 03 CA 74 01 36 00 78 B7 C8 23 36 20 10 FB C9 79 B7 28 G2 3E 08 CD 58 04 3E 20 CD 58 04 3E 08 CD 58 04 2B 0D 04 18 AE 21 C2 04 CD CC 03 C5 D5 E5 CD 4B FC 30 FB F5 CD A8 FC F1 E1 D1 C1 C9 F5 C5 D5 E5 B7 FA 64 04 FE 20 30 05 CD 39 FC 18 05 F6 00 CD 33 FC CD 4B FG 30 0F CD 47 04 FE 13 20 08 CD 47 04 FE 03 CA 74 01 E1 D1 C1 F1 C9 3A 98 09 4F 06 07 C3 20 FD 3A 99 09 CB 27 CB 27 CB 27 CB 27 57 3A 9A 09 B2 11 10 00 21 40 03 C3 26 FD 3A 9C 09 57 3A 9B 09 CB 27 CB 27 CB 27 CB 27 B2 11 10 00 21 50 03 C3 26 FD 50 72 65 73 73 20 61 6E 79 20 6B 65 79 20 74 6F 20 63 6F 6E 74 69 6E 75 65 2E 2E 2E 00 20 20 49 20 20 20 4B 65 79 <--data 62 6F 61 72 64 20 69 6E 70 75 74 0D 0A 20 49 49 20 20 20 50 start 72 69 6E 74

SAMPLE PROGRAM HEX CODE SECOND BLOCK

SAMPLE PROGRAM HEX CODE THIRD BLOCK

6D 61 6B 65 20 74 68 65 6D 20 61 6E 6F 74 68 65 72 20 63 6F 6C 6F 72 20 20 20 0D 0A 0A 00 0D 0A 0A 49 2F 4F 20 65 72 72 6F 72 00 0D 0A 0A 4F 70 65 72 61 74 69 6F 6E 20 43 6F 6D 70 6C 65 74 65 0D 0A 00 0D 0A 0A 46 69 6C 65 20 45 78 69 73 74 73 2G 20 75 73 65 20 61 6E 6F 74 68 65 72 20 6E 61 6D 65 30 0D 0A 0A 49 6E 70 75 74 20 46 69 6C 65 20 4E 61 6D 65 3A 20 00 0D 0A 46 69 6C 65 20 4E 6F 74 20 46 6F 75 6E 64 2C 20 74 72 79 20 61 67 61 69 6E 00 0D 0A 00 07 01 0F 01 07 0C

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EOS DIRECTORY STRUCTURE

When looking at BLOCK 1 (The Directory), group the bytes into groups of 26 bytes. The first 26 bytes is the VOLUME-RECORD. The next groups of 26 bytes are the FILE-RECORDS. The last FILE-RECORD has a filename of BLOCKS LEFT. This indicates the end and indicates how much is left on the tape/disk.

VOLUME-RECORD

VOLUME-	-RECORD	
V	OLUME-NAME	12 BYTES
	Inited name that shows	up on catalog as VOLUME.
D	IRECTORY-SIZE	1 BYTE
	VOLUME ATTRIBUTE	BIT 7
	VOL. DIRECTORY SIZE	BITS 6 – 0
	A 1 in the attrib	ute indicates delete protected.
	The directory size	ze is shown as # of blocks.
D	IRECTORY-CHECK	4 BYTES
	Unique code 55 AA 00 F	F indicates a directory exists on tape/disk.
V	OLUME-SIZE	4 BYTES
	Total # of blocks allocate	ed.
U	Inused ?	2 BYTES
D	ATE (CREATION ?)	3 BYTES
	1 each for Year, Month	and Day.
FILE-RECC	ORD	
F	ILE-NAME	12 BYTES
	Name of file, usually foll	lowed by file type (A, A , H, H), then a HEX 03.
F	ILE-ATTRIBUTE	1 BYTE
	1 in the bit position indi	cates true conditions as:
	7 – Perm. (DELE 6 – Write Protec 5 – Read Protec 4 – User File 3 – System File 2- File flagged a 1 – Execute prot	TED) Protected cted ted s deleted tected (1 is no execute)

0 – Not a file (See BLOCKS-LEFT entry) START-BLOCK 4 BYTES

Starting block number for file. Left (Hi-order) bytes usually has the value, other 3 are 00.

ALLOCATED-SIZE 2 BYTES

Number of blocks actually allocated.

USED-SIZE 2 BYTES

Number of blocks used (Full + Partial)

BYTES-IN-LAST-BLOCK 2 BYTES

Number of bytes in last block. Max value in here is 00 04. This would indicate 1024

bytes (full).

DATE (CREATED ?) 3 BYTES

1 for Year, Month and Day.

NOTE: For START-BLOCK, ALLOC/USED SIZE and BYTES-LAST.

The 2 bytes are always shown as lo-value/hi-value.

The value = left byte + (right byte * 256).

I.e. 00 04 is 0 + (4 * 256) = 1024

This coding is fairly standard in Z*) coding.

Things to look for:

DIRECTORY-SIZE most are 81 (1000 0001) which indicates delete protect, 1 block directory.

VOLUME-SIZE Tape normally FF 00 or 00 01. Disk A0. If using PACKCOPY, the copied disk from tape gets the tape FF 00.

FILE-NAME Sometimes you see parts of the name BLOCKS-LEFT remaining at the right end. This is ignored as the system reads up to the first HEX 03 (left to right). If it is a USER-FILE, the character to the left of the HEX 03 is the FILE-TYPE. Some system files have a HEX 02 here. This shows up under DISK-MGR as a circle with bars in it.

FILE-ATTRIBUTE This is where you need to break the hex into the bit patterns. This is what the system determines what files are printed under CATALOG. Deleted files still exist but not accessible from BASIC. You can BLOCK-READ then and dump them out. LOCKED files set on the first 3 protects.

START-BLOCK This will tell you what block to start reading from. Remember to do a HEX convert.

DATE (CREATE) This may contain values.

BLOCKS-LEFT This is the last filename entry. Its is marked as ATTRIBUTE (01) not a file. The START-BLOCK shows the next available block for storage. ALLOCATED-SIZE shows the number of available blocks left.

Interleave Chart

Туре	Size	Heads	Tracks	Sectors/Track	Interleave
Standard 5.25"	160K	1	40	8	5
Double sided 5.25"	320K	2	40	8	5
Quad size 5.25"	640K	2	80	8	4
Double sided 3.5"	720K	2	80	9	4
High density 3.5"	1.44M	2	80	18	4

160K Disk Interleave Example

Track 0							
0	200	400	600	800	A00	C00	E00
Block 0	Block 2	Block 1	Block 3	Block 2	Block 0	Block 3	Block 1
low	high	low	high	low	high	low	high
Sector 1	Sector 2	Sector 3	Sector 4	Sector 5	Sector 6	Sector 7	Sector 8
Track 1							
1000	1200	1400	1600	1800	1A00	1C00	1E00
Block 4	Block 6	Block 5	Block 7	Block 6	Block 4	Block 7	Block 5
low	high	low	high	low	high	low	high
Track 2							
2000	2200	2400	2600	2800	2A00	2C00	2E00
Block 8	Block 10	Block 9	Block 11	Block 10	Block 8	Block 11	Block 9
low	high	low	high	low	high	low	high
Track 3							
3000	3200	3400	3600	3800	3A00	3C00	3E00
Block 12	Block 14	Block 13	Block 15	Block 14	Block 12	Block 15	Block 13
low	high	low	high	low	high	low	high
		directory	file			file	
Track 4							
4000	4200	4400	4600	4800	4A00	4C00	4E00
Block 16	Block 18	Block 17	Block 19	Block 18	Block 16	Block 19	Block 17
low	high	low	high	low	high	low	high
file	file	file		file	file	file	file
5000	5200	5400	5600	5800	5A00	5C00	5E00

5000	5200	5400	5600	5800	5A00	5C00	5E00
Block 20	Block 22	Block 21	Block 23	Block 22	Block 20	Block 23	Block 21
low	high	low	high	low	high	low	high

file file file file file

ASCII CHART

HEX	CHARACTER	MEANING	DEC	HEX	CHARACTER	MEANING
00	CONTROL-@		39	27	I.	
01	CONTROL-A		40	28	(
02	CONTROL-B		41	29)	
03	CONTROL-C		42	2A	*	
04	CONTROL-D		43	2B	+	
05	CONTROL-E		44	2C	I.	
06	CONTROL-F		45	2D	-	
07	CONTROL-G	BELL	46	2E		
08	CONTROL-H	BACKSPACE	47	2F	/	
09	CONTROL-I	HORIZ TAB	48	30	0	
0A	CONTROL-J	LINE FEED	49	31	1	
0B	CONTROL-K		50	32	2	
		CLEAR				
0C	CONTROL-L	SCREEN	51	33	3	
0D	CONTROL-M	RETURN	52	34	4	
0E	CONTROL-N		53	35	5	
OF	CONTROL-O		54	36	6	
10	CONTROL-P	DUMP TO PRT	55	37	7	
11	CONTROL-Q		56	38	8	
12	CONTROL-R		57	39	9	
13	CONTROL-S	PAUSE	58	3A	:	
14	CONTROL-T		59	3B	;	
15	CONTROL-U		60	3C	<	
16	CONTROL-V		61	3D	=	
17	CONTROL-W		62	3E	>	
18	CONTROL-X		63	3F	?	
19	CONTROL-Y		64	40	@	
1A	CONTROL-Z		65	41	А	
1B	CONTROL-[ESCAPE/WP	66	42	В	
1C	CONTROL-\		67	43	С	
1D	CONTROL-]		68	44	D	
1E	CONTROL-^		69	45	E	
1F	CONTROL		70	46	F	
20	SPACE		71	47	G	
21	!		72	48	н	
22	п		73	49	I	
23	#		74	4A	J	
24	\$		75	4B	К	
25	%		76	4C	L	
26	&		77	4D	М	
	HEX 00 01 02 03 04 05 06 07 08 09 0A 08 07 08 09 0A 0B 0C 0D 0E 0F 10 11 12 13 14 15 16 17 18 19 1A 15 16 17 18 19 1A 15 16 17 21 22 23 24 25 26	HEX CHARACTER 00 CONTROL-@ 01 CONTROL-A 02 CONTROL-B 03 CONTROL-C 04 CONTROL-D 05 CONTROL-E 06 CONTROL-F 07 CONTROL-I 08 CONTROL-I 09 CONTROL-I 00 CONTROL-I 00 CONTROL-I 00 CONTROL-I 00 CONTROL-I 00 CONTROL-I 00 CONTROL-I 01 CONTROL-I 02 CONTROL-I 03 CONTROL-I 04 CONTROL-I 05 CONTROL-N 06 CONTROL-N 07 CONTROL-N 08 CONTROL-O 10 CONTROL-Q 11 CONTROL-Q 12 CONTROL-V 13 CONTROL-V 14 CONTROL-V 15 CONTROL-Y <td>HEX CHARACTER MEANING 00 CONTROL-@ 01 CONTROL-A 02 CONTROL-B 03 CONTROL-C 04 CONTROL-B 05 CONTROL-F 06 CONTROL-H 07 CONTROL-H 08 CONTROL-I 09 CONTROL-I 00 CONTROL-K 01 CONTROL-N 08 CONTROL-N 09 CONTROL-K 00 CONTROL-N 01 CONTROL-N 02 CONTROL-N 03 CONTROL-N 04 CONTROL-N 05 CONTROL-N 06 CONTROL-N 07 CONTROL-N 08 CONTROL-N 09 CONTROL-N 01 CONTROL-N 02 CONTROL-N 03 CONTROL-N 04 CONTROL-N 05 CONTROL-N 10 CONTROL-N 11 CONTROL-N 12</td> <td>HEX CHARACTER MEANING DEC 00 CONTROL-@ 39 01 CONTROL-A 40 02 CONTROL-B 41 03 CONTROL-C 42 04 CONTROL-D 43 05 CONTROL-F 44 06 CONTROL-F 45 07 CONTROL-I BELL 46 08 CONTROL-I HORIZ TAB 48 0A CONTROL-J LINE FEED 49 0B CONTROL-K 50 CLEAR 0C CONTROL-M RETURN 52 0E CONTROL-N S33 0F CONTROL-N 53 0F CONTROL-N S2 0E CONTROL-N 53 0F CONTROL-N S3 0F CONTROL-N 53 0F CONTROL-N S4 10 CONTROL-N 55 11 CONTROL-N S6 12 CONTROL-N 66</td> <td>HEX CHARACTER MEANING DEC HEX 00 CONTROL-Q 39 27 01 CONTROL-A 40 28 02 CONTROL-B 41 29 03 CONTROL-C 42 2A 04 CONTROL-D 43 28 05 CONTROL-F 45 2D 07 CONTROL-F 45 2D 07 CONTROL-H BACKSPACE 47 2F 09 CONTROL-I HORIZ TAB 48 30 0A CONTROL-M BACKSPACE 47 2F 09 CONTROL-M BACKSPACE 47 2F 08 CONTROL-M BACKSPACE 47 2F 09 CONTROL-M SCREN 51 33 0A CONTROL-N S3 35 0F CONTROL-N S3 35 0F CONTROL-N S7 39 10 CONTROL-Y</td> <td>HEX CHARACTER MEANING DEC HEX CHARACTER 00 CONTROL-@ 39 27 ' 01 CONTROL-A 40 28 (02 CONTROL-B 41 29) 03 CONTROL-C 42 2A * 04 CONTROL-D 43 28 + 05 CONTROL-F 45 2D - 06 CONTROL-G BELL 46 2E . 07 CONTROL-H BACKSPACE 47 2F / 08 CONTROL-J LINE FEED 49 31 1 08 CONTROL-K 50 32 2 2 04 CONTROL-K EEAR 5 3 3 05 CONTROL-N RETURN 52 34 4 06 CONTROL-N ST 35 5 5 07 CONTROL-N ST 36</td>	HEX CHARACTER MEANING 00 CONTROL-@ 01 CONTROL-A 02 CONTROL-B 03 CONTROL-C 04 CONTROL-B 05 CONTROL-F 06 CONTROL-H 07 CONTROL-H 08 CONTROL-I 09 CONTROL-I 00 CONTROL-K 01 CONTROL-N 08 CONTROL-N 09 CONTROL-K 00 CONTROL-N 01 CONTROL-N 02 CONTROL-N 03 CONTROL-N 04 CONTROL-N 05 CONTROL-N 06 CONTROL-N 07 CONTROL-N 08 CONTROL-N 09 CONTROL-N 01 CONTROL-N 02 CONTROL-N 03 CONTROL-N 04 CONTROL-N 05 CONTROL-N 10 CONTROL-N 11 CONTROL-N 12	HEX CHARACTER MEANING DEC 00 CONTROL-@ 39 01 CONTROL-A 40 02 CONTROL-B 41 03 CONTROL-C 42 04 CONTROL-D 43 05 CONTROL-F 44 06 CONTROL-F 45 07 CONTROL-I BELL 46 08 CONTROL-I HORIZ TAB 48 0A CONTROL-J LINE FEED 49 0B CONTROL-K 50 CLEAR 0C CONTROL-M RETURN 52 0E CONTROL-N S33 0F CONTROL-N 53 0F CONTROL-N S2 0E CONTROL-N 53 0F CONTROL-N S3 0F CONTROL-N 53 0F CONTROL-N S4 10 CONTROL-N 55 11 CONTROL-N S6 12 CONTROL-N 66	HEX CHARACTER MEANING DEC HEX 00 CONTROL-Q 39 27 01 CONTROL-A 40 28 02 CONTROL-B 41 29 03 CONTROL-C 42 2A 04 CONTROL-D 43 28 05 CONTROL-F 45 2D 07 CONTROL-F 45 2D 07 CONTROL-H BACKSPACE 47 2F 09 CONTROL-I HORIZ TAB 48 30 0A CONTROL-M BACKSPACE 47 2F 09 CONTROL-M BACKSPACE 47 2F 08 CONTROL-M BACKSPACE 47 2F 09 CONTROL-M SCREN 51 33 0A CONTROL-N S3 35 0F CONTROL-N S3 35 0F CONTROL-N S7 39 10 CONTROL-Y	HEX CHARACTER MEANING DEC HEX CHARACTER 00 CONTROL-@ 39 27 ' 01 CONTROL-A 40 28 (02 CONTROL-B 41 29) 03 CONTROL-C 42 2A * 04 CONTROL-D 43 28 + 05 CONTROL-F 45 2D - 06 CONTROL-G BELL 46 2E . 07 CONTROL-H BACKSPACE 47 2F / 08 CONTROL-J LINE FEED 49 31 1 08 CONTROL-K 50 32 2 2 04 CONTROL-K EEAR 5 3 3 05 CONTROL-N RETURN 52 34 4 06 CONTROL-N ST 35 5 5 07 CONTROL-N ST 36

DEC	HEX	CHARACTER	MEANING	DEC	HEX	CHARACTER	MEANING
78	4E	Ν		110	6E	n	
79	4F	0		111	6F	0	
80	50	Р		112	70	р	
81	51	Q		113	71	q	
82	52	R		114	72	r	
83	53	S		115	73	S	
84	54	Т		116	74	t	
85	55	U		117	75	u	
86	56	V		118	76	v	
87	57	W		119	77	w	
88	58	Х		120	78	х	
89	59	Y		121	79	У	
90	5A	Z		122	7A	Z	
91	5B	[123	7B	{	
92	5C	١		124	7C	I	
93	5D]		125	7D	}	
94	5E	٨		126	7E	~	
95	5F	_		127	7F	DELETE	
96	60	I		128	80	HOME	
97	61	а		129	81	FUNCTION I	
98	62	b		130	82	FUNCTION II FUNCTION	
99	63	C		131	83	III FUNCTION	
100	64	d		132	84	IV	
101	65	е		133	85	FUNCTION V FUNCTION	
102	66	f		134	86	VI	
103	67	g		135	87		
104	68	h		136	88	SHIFT	
105	69	i		137	89	FUNCTION 1 SHIFT	
106	6A	j		138	8A	FUNCTION II SHIFT	
107	6B	k		139	8B	FUNCTION III SHIFT FUNCTION	
108	6C	I		140	8C	IV	
109	6D	m		141	8D	FUNCTION V	

DEC	HEX	CHARACTER	MEANING
		SHIFT FUNCTION	
141	8D	V	
		SHIFT FUNCTION	
142	8E	VI	
143	8F		
144	90	WILDCARD	
145	91	UNDO	
146	92	COPY	
147	93	GET	
148	94	INSERT	
149	95	PRINT	
150	96	CLEAR	
151	97	DELETE	
152	98	SHIFT WILDCARD	
153	99	SHIFT UNDO	
154	9A	SHIFT MOVE	
155	9B	SHIFT STORE	
156	9C	SHIFT INSERT	
157	9D	SHIFT PRINT	
158	9E	SHIFT DELETE	
159	9F		
160	A0	ARROW UP	
161	A1	ARROW RIGHT	
162	A2	ARROW DOWN	
163	A3	ARROW LEFT	

COLOR PALETTE

0	Transparent	8	Medium Red
1	Black	9	Light Red
2	Medium Green	10	Dark Yellow
3	Light Green	11	Light Yellow
4	Dark Blue	12	Dark Green
5	Light Blue	13	Purple
6	Dark Red	14	Gray
7	Cyan	15	White

MEMORY BANK SWITCHES

The Z80 can only address 64K (2¹⁶) memory locations but can change blocks of memory by a technique known as bank switching. The ADAM contains about 40K of ROM (Read Only Memory) with Smartwriter and two operating system, EOS and OS7 that can be switched into the upper or power 32K of memory space. Expansion RAM (if you have it) and game cartridge ROM can also be switched in and out of the active memory space. Memory is normally all RAM in BASIC, the OS having been copied from ROM to RAM.

The bank switch is an OUT 7F,x command, where the lower nibble of x selects the following options:

Lower 32 K	D1	D0	Upper 32K	D3	D2
Smartwriter, EOS		0	32K RAM	0	0
32K RAM	0	1	Expansion ROM	0	1
Expansion RAM	1	0	Expansion RAM	1	0
OS7+24K RAM	1	1	Cartridge ROM	1	1

For example, to select normal RAM for both the upper and lower blocks the number in binary is 0001, or 1. To select 32K of RAM on the bottom and cartridge ROM on the top, the number is 1101, or 13 (dec). A D1 and D) of 0 will access wither Smartwriter or the EOS ROM, depending upon another in/out command. Performing OUT 3F,2 before the OUT 7F,0 will access the EOS ROM. OUT 3F,0 causes OUT 7F,0 to access the Smartwriter ROM.